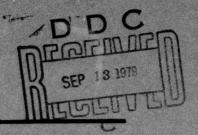


Semiannual Technical Summary



See 1473 in Jack

Seismic Discrimination

31 March 1979

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Prepared for the Defense Advanced Research Projects Agency under Electronic Systems Division Contract F19628-78-C-0002 by

Lincoln Laboratory

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

LEXINGTON, MASSACHUSETTS



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SEISMIC DISCRIMINATION

SEMIANNUAL TECHNICAL SUMMARY REPORT TO THE DEFENSE ADVANCED RESEARCH PROJECTS AGENCY

1 OCTOBER 1978 - 31 MARCH 1979

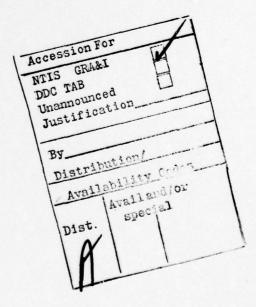
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ABSTRACT

Lincoln Laboratory has embarked on the task of carrying out the design and specification of a U.S. Data Center which will fulfill U.S. obligations that may be incurred under a possible future Comprehensive Test Ban Treaty. This report includes 17 contributions, relating progress in the Data Center design and associated seismic research. These contributions are grouped as follows: seismic data management system (5 studies), locations and travel times (5 studies), and general seismology (7 studies).



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SUMMARY

This is the thirtieth Semiannual Technical Summary report describing the activities of Lincoln Laboratory funded under Project Vela Uniform. This report covers the period 1 October 1978 to 31 March 1979. Project Vela is a program of research into the discrimination between earthquakes and nuclear explosions by seismic means. A recent new emphasis of the project is in the development of the data-handling and analysis techniques that might be appropriate for the monitoring of a potential Comprehensive Test Ban Treaty, presently under negotiation. The Lincoln Laboratory program during FY 79 has two objectives. The first is to carry out a detailed design study, and produce hardware and software specifications for a Data Center which will fulfill U.S. obligations that may be incurred under the Comprehensive Test Ban Treaty, and under any international agreements that may be associated with this treaty. The second is to carry out seismic research, with particular emphasis on those areas directly related to the operations of the Data Center.

Section I of this report summarizes, in general terms, the functions of the Data Center insofar as they can be formulated at present. Both alphanumeric and waveform data, some in real time, will be transmitted to the Data Center. The main products of the Data Center will be one or more event lists, an archive for all the input data, and a set of event-associated waveform files which will be useful for research and development. The architecture of the Center is being formulated using state-of-the-art computer technology, and will be described in detail in a special report to be issued late in FY 79. For the present, we focus on Center requirements using current estimates of data-flow rates, and we describe some important interface issues that are yet to be completely resolved. Seismicity variations are substantial, and may at times place a severe load on the processing capability of the Center. The average number of events detected per day, including local events, is likely to lie in the range 50 to 100. It is shown that episodes of 2 or 3 times this activity are relatively common. We are also concerned about the process of event detection, and a study compares the computational load generated by a variety of detection algorithms. Research into the effectiveness of these algorithms is continuing.

One of the major tasks of the Data Center will be to locate seismic events. A number of studies related to this task are described in Sec. II. Two investigations apply the master-event technique — one to the improvement in epicenter accuracy that can be obtained using regional data, and the other to the improvement in focal-depth resolution that is possible. A discussion of the information content in arrival-time data is also included. An attempt to improve the regionalization of Rayleigh-wave travel times is described, and an extensive review of station travel-time anomalies is given. Using the ISC Catalog for 1964-75, a new set of travel-time anomalies is given for 751 stations. These anomalies include both first- and second-order terms in azimuth, as well as a zeroth-order term. The tables included constitute the most comprehensive data on station travel-time anomalies currently available.

Section III contains studies in a number of different areas. Amplitude spectra of crustal phases observed from an earthquake in Eastern Canada at a distance of 5° show substantial signal at frequencies as high as 30 Hz. Observed Q values for each of the crustal phases are very high. Another study relates the beginning of investigations into scatter and bias in body-wave magnitude m_b. A development of previous work on the estimation of yields from short-period body-wave amplitudes is described. In another study, the dispersion of mantle Love

waves has been completed. Lateral variations in structure beneath continents and oceans below about 200 km are not required by the data. An analysis of broad-band SRO data is described. Also, some suggested transfer functions for instruments designed for seismic monitoring at regional distances are given in detail.

We continue to develop the capabilities of our in-house PDP-11 computer system. Much of the software used on this system will have application in the Data Center. Some details of recent applications software for the handling of waveforms within the UNIX operating system are given.

M.A. Chinnery

SEISMIC DISCRIMINATION

I. SEISMIC DATA MANAGEMENT SYSTEM

A. SEISMIC DATA MANAGEMENT SYSTEM (SDMS): PROGRESS REPORT

Lincoln Laboratory is engaged in the design and specification of a SDMS which will be documented in detail in a Technical Report scheduled to be issued near the end of FY 1979. This is a brief summary of the requirements and design goals which are guiding the current design effort.

The SDMS is being designed to implement data management, computational, and analysis support functions for large amounts of seismic waveform and parametric data. The principal goal of the design effort is to provide a state-of-the-art seismic data management and computational facility to support the U.S. commitments for International and National Data Centers which may arise from the signing and ratification of a Comprehensive Nuclear Test Ban Treaty (CTBT) presently under negotiation. The requirements stated here derive from the current (incomplete) definition of those functions as they are being negotiated. A principal source of the international requirements is document CCD/558 entitled Report to the Conference of the Committee on Disarmament by an Ad Hoc Group of Scientific Experts to Consider the International Cooperative Measures to Detect and Identify Seismic Events dated 14 March 1978. It is recognized that these recommendations are subject to revision as a result of the treaty negotiations. It is anticipated that the SDMS will implement the data management, computational, and analysis support functions required by both the U.S. national commitments and International Data Center aspects of such a treaty. The SDMS will also serve as an archive for seismic data and a support facility for the use of the archived data in advanced system development and seismic research.

There are two conceptual entities to be supported by the SDMS. They are the International Data Center and the National Data Center. These will be defined in the projected CTBT. The International Data Center, based on the CCD report, is expected to collect seismic data from the participating nations and process the data to provide a daily list of seismic events worldwide. The seismic data are expected to be provided by cooperating nations from stations operated by their seismic analysts. These data are planned to be distributed to the International Centers, now expected to number three, over communication facilities provided through agreement with the World Meteorological Organization (WMO) which currently operates a worldwide teletype communication network for exchange of international meteorological data. The data to be exchanged are expected to be messages containing measurements of seismic parameters describing observed seismic-wave arrivals at the various stations. The International Centers are planned to use these data to locate seismic events worldwide and calculate the seismic parameters of the events, i.e., location, time, magnitude, etc., including seismic parameters which may be useful in discriminating between naturally occurring seismic events and underground explosions. A detailed events list will be produced and distributed with a total delay of three to five days. The International Data Center is expected to serve as a distribution center for the exchange of detailed seismic data used in the monitoring of the treaty obligations. These data are planned to include both waveform and parametric data.

The National Data Center is expected to provide the U.S. input to the International Data Center as well as fulfilling other national goals in the seismic research area. The National Data Center is planned to receive the digitized seismic waveform data from a number of national stations, and probably from other stations as well. The number and exact characteristics of these participating stations are unknown at this time. The identification of the stations and the details of the waveform data from them will not be certain until after the treaty is signed. All of these waveform data are planned to be available for analysis and to be archived for further research as appropriate. The research and analysis users of the system will be provided with state-of-the-art computational facilities by the system, as well as access to the archived data. The data flow into and out of the SDMS is shown schematically in Fig.I-1.

There are two major aspects of the operation of the SDMS which is shown in functional form in Fig.I-2. The SDMS is planned to provide integrated support to the requirements of both the International Data Center and to the U.S. National Data Center. Certain requirements arise from the need to routinely collect, store, and process the incoming waveform data. These requirements come from the National Data Center requirements. The SDMS must provide communication, waveform data handling, display, and computational support. It is most important for the SDMS to capture the real-time waveform data reliably. These waveform data are planned to be processed for the automatic detection of seismic activity. The requirements for the system to capture and store the incoming data for waveform analysis until the event list is issued, up to five days later, places severe demands on the overall system reliability and on the capacity and data rate of the data-storage system. The automatic detection processing places requirements for large amounts of computational capacity in the system.

From the event processing of the seismic data, other activities arise which create requirements associated with the International Data Center commitment. They are archive storage and computational requirements. The International Data Center is planned to archive and make available the parametric and waveform data associated with the published event list. This archive grows steadily during the life of the system, and is planned to be used to supply requests for data to interested participant countries and to analysts and researchers.

The requirement to publish a daily event list and the need to support the analysis of the listed events place a requirement for significant computational power on the system. The automatically detected seismic-wave arrivals are expected to be refined by inspection by expert seismic analysts, who will update the automatically calculated parameters and measure or compute those parameters which are not determined automatically by the detection process. These measurements, along with those supplied by other participants, other participating countries, and possibly other Government agencies, will be processed to associate those arrivals coming from the same event. The associated arrivals will be used to locate the event and to calculate the seismic description of the event. This waveform processing and event list preparation will require significant computer processing. Since the number of stations providing waveform data is as yet undetermined, this further reinforces the requirement for flexibility and expandability in the design of the SDMS.

Another aspect of the design is that the exact level of the requirements cannot be ascertained at this time because the treaty is not final, but the design should be completed prior to completion of the treaty to facilitate implementation when the treaty goes into force. The treaty requirements will place floor under the minimum level of support required. The SDMS must be

easily modified to support the minimum level of treaty-specified requirements, and then grow or shrink to accommodate changes in the level of support arising from changing requirements. The incomplete state of the treaty impacts the National Data Center requirements in that the number and specification of the real-time waveform data sources cannot be determined yet. All these factors force the system design to allow great flexibility and expandability in the system implementation.

The architecture and other design issues of the SDMS are currently being pursued by the Lincoln Laboratory staff in consultation with a wide range of sources from Government agencies, private industry, and academic organizations. This consultation is taking place in the areas of data management, digital-signal processing, display technology, and distributed computer systems technology. The overall goal of the SDMS is to provide a truly efficient, state-of-the-art seismic data management and analysis system. This can only result as a proper synthesis of modern computer technology with the latest in seismological data processing and display techniques. The specifications and design issues of the SDMS will be fully documented in a Technical Report which is expected to be issued near the end of this fiscal year.

A.G. Gann

B. DATA RATES OF WAVEFORM DATA COMING INTO SDMS

The design of SDMS can only proceed with an accurate evaluation of the amount of data it will handle. While the exact makeup of the data has not been completely specified, a reasonable estimate can be made. The current assumption is that the data coming into the SDMS will emanate from 52 stations, each with 9 separate data channels. The breakdown of each station's data by channel is:

- (1) 3 channels of long-period (LP) data sampled once per second,
- (2) 3 channels of medium-period (MP) data sampled four times per second, and
- (3) 3 channels of short-period (SP) data sampled forty times per second.

The total amount of data from each station is given by:

SP = 3 channels * 40 samples/sec * 16 bits/sample = 1920 bps

MP = 3 channels * 4 samples/sec * 16 bits/sample = 192 bps

LP = 3 channels * 1 sample/sec * 16 bits/sample = 48 bps

Station Total = 1920 + 192 + 48 = 2160 bps

Total Data Rate = 52 stations * 2160 bps per station = 112.32 kbps.

To allow for control and status information in the total data-rate estimate, a value of 125 kbps will be used for all SDMS design calculations.

1. Disk Capacities for SDMS

One of the SDMS requirements is the preparation of a 3- to 5-day bulletin. This requirement can only be met if at least 5 days of the incoming waveform data are stored on disk where they can be accessed with a minimum delay. The amount of disk capacity this requires is then:

The disk to be used in SDMS has an unformatted capacity of 675 Mbytes. Assuming that the formatted capacity is 635 Mbytes, SDMS will require at least 11 of these disks for storing the online waveform data.

2. Disk Throughput

The disk throughput during any I/O operation is controlled by the size of the buffer being written out to the disk. The seek and rotational latency times are much greater than the time it takes to transmit data from memory to the disk. Since each individual I/O operation involves one seek and a half-a-disk rotation time, the larger the amount of data transferred in one I/O operation the greater the data throughput. The seek time on the disks we are discussing is 18 msec. The rotational latency is 8.3 msec. The data transfer rate is 1209 kbytes/sec. The formula for calculating the time needed to transfer one block of data is:

36.3 msec/block (seek + latency) + 0.0008 msec/byte * No. bytes/block

Table I-1 shows the disk bandwidth for varying buffer sizes.

	BLE I-1
DISK BANDWIDTH AS A	FUNCTION OF BUFFER SIZE
Buffer Size (bytes)	Disk Bandwidth (bytes/sec)
512	13942.7
1024	27544.0
2048	53861.0
4096	103127.9
8192	190045.4

3. Tape Storage Requirements

All the waveform data will be archived on tape for at least 6 months. This will require a large number of tapes. The total number of tapes will be minimized by using 9-track 6250-bpi tapes with 8192 byte records. The rate of tape use is found to be:

The number of tapes per day is calculated with the following equations:

$$\frac{125 \text{ kbps} * 86400 \text{ sec/day}}{8 \text{ bits/byte}} = 1350 \text{ Mbytes/day}$$

$$\frac{1350 \text{ Mbytes/day}}{117.55 \text{ Mbytes/tape}} = 11.5 \text{ tapes/day}$$

Allowing for a margin of error and for simplicity in handling, the actual rate of tape usage will therefore be about 20 tapes/day.

J. Sax

C. SDMS INTERFACE ISSUES

The SDMS will have a number of interfaces with external organizations. These include participants in the International Data Exchange function, the U.S. National Earthquake Information Service (NEIS), the Department of Energy (DOE), and others. In many cases, the technical interface is simple and is not a consequential system issue. Two of the interfaces with substantial technical impact are discussed here and will be considered in much more detail during the ongoing system design effort. They are the communication interface for alphanumeric data for participants in the International Data Exchange, and the communication interface to the DOE system which will supply near-real-time data from National Seismic Systems.

The current plan for International Data Exchange as outlined in the CCD Working Paper 558 is to use communication services of the World Meteorological Association (WMO) for the exchange of alphanumeric data and event lists prepared by International Data Centers. That network is a low-speed worldwide network currently used for distribution of meteorological data and some small amounts of alphanumeric seismic data. We have accepted the CCD/558 concept and plan to interface to the WMO system. It is not strictly part of our function to evaluate the current WMO network capability or to suggest technical changes. However, since the Data Center services will be influenced by their communication services, we will evaluate available WMO services in the course of our system development and, if appropriate, suggest modifications or improvements.

The DOE communication system interface is technically more complex. It is this interface which will furnish near-real-time seismic signals from up to 45 National Seismic Stations to be designed, installed, and operated by DOE. Each such station generates some 2.4 kbps of data in the form of a 2.4-kbit message once each second. For technical reasons, messages may be delayed from real time by as much as 20 min. The data in a message include 1 sample from each of 3 long-period (LP) sensors, 4 samples from each of 3 medium-period (MP) sensors, and 40 samples from each of 3 short-period (SP) sensors. The message delay, bits per message, messages per second, number and type of channels, and sampling rates are details which are not critical for most issues discussed below, but do represent reasonable specific values which can be used to simplify the discussion.

The DOE interface issues which have been identified and are discussed below are:

- (1) Number, type, and capacity of hardware interface,
- (2) Reorganization and reformatting of basic data,
- (3) Reliability and retransmission capability,
- (4) Message formats and interface protocols, and
- (5) Seismic quality control.

The number, type, and capacity of communication interfaces must be determined. The waveform data for SDMS could be multiplexed and made available over a single high-speed line. For forty-five 2.4-kbit data sources, this would require a line with at least 108 kbits capacity. Substantially more might be required to allow for catching up for downtime. Another alternative would be a separate medium-speed (say 2.4 or 4.8 kbits to allow for retransmission or catchup for downtime) line data from each station. Single stations could be split over more than one lower-speed line into the SDMS, but there does not seem any reasonable reason to do this. Also, some number of stations (say 2 to 20) could be multiplexed on a medium- to high-speed line into the SDMS. Our current expectation is that DOE will furnish the data multiplexed onto a single high-speed line or a small number of relatively high-speed lines.

The second issue is reorganization. As mentioned above, the natural unit of data generated by a station is a 2.4-kbit message containing 1 sec of data for all the seismic channels. However, within the SDMS we will generally deal with data which have been organized differently. Using the message contents mentioned above as an example, preferred SDMS basic data units might be as follows. The SDMS will deal with data units which are all samples, in order, from a single seismic channel for a time interval. The desired individual units might contain 4000 data samples (8000 8-bit bytes). Such large units are desirable for efficiency and response considerations. A 4000-sample unit might represent about 100 sec of a SP channel, or about 16 min. of mid-band, or about 66 min. of a LP channel. Time series shorter than nominal length might be used occasionally, such as when there is a known data gap and a unit is terminated short because of it. Also, shorter units (say, 2000 samples) might be used for LP data. We presently plan to perform data reorganization as part of the basic SDMS interface function rather than request that the reorganization be done on the DOE side of the interface. This will result in sizable memory requirements in our interface.

Thirdly, the SDMS need for redundant data-acquisition hardware and buffering by the SDMS interface units depends upon the DOE capability to retransmit data which might be lost due to an interface unit failure. The amount of data lost due to an interface unit failure might range from a few tens of seconds of high-frequency data, to as much as 30 min. of LP data. The maximum possible would depend on the number of samples in a normal demultiplexed unit of any particular kind of channel. It could easily be kept below 15 min. if desired. If the DOE system includes disks and storage of data for at least that length of time, it may be possible to use that capability and avoid unneeded extra hardware and complexity on the SDMS interface. All that would be needed would be the ability to request transmission starting at some point 15 to 30 min. in the past. With a communication line of twice the required average rate, the system would quickly catch up.

Fourthly, there are message format and interface data transfer protocols. DOE has specified a preliminary format for the 2.4-kbit basic message from a station. This is being accepted for now, with the understanding that it may be changed. In addition to the data-format question, there are various levels of communication protocols which must be specified. Such protocols include traditional low-level communication handshaking, ack-nak, retransmission rules. However, they also include much higher-level, task-oriented protocols. These will initiate and accomplish the equivalent of file transfers for large amounts of data from DOE to SDMS and, in the context of monitor functions discussed below, modest or small amounts of data from SDMS to DOE. (Monitor information may go by a separate route, independent of the primary seismic data interfaces and communication lines.)

Finally, seismic quality control is a critical SDMS function. Data must be processed by programs and selectively reviewed by seismic analysts to monitor and maintain its quality in the context of the use to which it is being put. Such monitoring is basically seismic and is distinct from communication issues, correction and detection of communication errors, or algorithmic data authentication. We believe that the SDMS should incorporate the seismic monitoring of the data as part of its functions, and that all other technical monitoring, including error detection and correction, be done within the DOE system. Results of the seismic monitoring, the identification of channels whose seismic content has deteriorated so that maintenance action is indicated, will be passed to the DOE system for action. Closely related is the requirement that DOE operational and maintenance functions be coordinated with SDMS operations so that they do not inadvertently influence seismic capability in an adverse manner.

R.T. Lacoss

D. EARTHQUAKE OCCURRENCE RATES AND SDMS REQUIREMENTS

Storage capacities (disk and tape) and computational capability for the proposed SDMS are predicated by the incoming data rates. The latter depend not only upon the number of contributing seismic stations, but also upon the rate at which seismic events occur. The <u>average</u> numbers of events per day located by the two primary agencies responsible for routine association and location – the USGS Preliminary Determination of Epicenters (PDE) and the International Seismological Center (ISC) – have, during 1964-1977, been ~14 and ~20, respectively. The International Seismic Month (ISM) study, carried out by Lincoln Laboratory, yielded 996 events during a 29-day interval in 1972, or an average of 34 events/day. It seems reasonable to assume that the last rate will be exceeded due to increased operator performance under the stimulus of international seismic monitoring; in addition, the installation of a number of stations specifically designed to monitor local and regional events will substantially increase the number of small events recorded only at short distances. The average number of events located per day may thus reasonably be expected to be within the range of 50 to 100.

We have studied the PDE event list for 1964-1977 in order to determine the nature of fluctuations about the average in the number of events located per day. Figure I-3 shows the histogram of occurrences of a particular number of events/day during this time interval. The histogram is markedly skewed toward higher occurrence rates, and on 4 days more than 100 events have been located. Such a lopsided distribution is not readily amenable to statistical interpretation, and efforts to determine, e.g., given a certain number of events/day, the mean and standard deviation of the time to the next day with activity at least as great, were unsuccessful. The reason for this is that, at least at smaller magnitudes, earthquakes do not occur randomly: a sudden increase in events located often indicates that a large earthquake, with many associated aftershocks, has occurred, and the activity will continue at an enhanced rate for several days or weeks afterward. Earthquake swarms, generally associated with volcanism in regions of subduction or spreading, do not have a mainshock and are usually of short duration.

In estimating the data-storage and computational capacities of the SDMS, we must thus take into account these large variations in activity as well as the average activity, and further recognize that the sudden increases in activity are not strictly random but may continue for days or even weeks. Considerable excess short-term storage and computational capacity are required to deal with these large variations. Daily activity in excess of 100 events/day occurred in 1964 (Alaska), 1965 (Rat Island), and (from SDAC Bulletin) in 1978 (Kuriles). Such activity may

be considered sufficiently rare that the extra capability required to deal with it is economically unfeasible, but the last period of such activity, in the Kuriles, took place in a region which has frequently been discussed in evasion scenarios of the hiding-in-earthquake type.

We have studied the activity during large mainshock-aftershock sequences in the Kuril-Kamchatka region in some detail. This region accounts for over 10 percent of events of $m_b \geqslant 4.5$ reported in the PDE Bulletin during 1964-1977, and is of particular interest for the reasons noted above. Figure I-4 shows the decay of daily activity from the maximum for the 5 occasions on which a mainshock occurred with 25 or more aftershocks occurring within a day of the mainshock. A lower bound to the observed rate of decay of activity from the maximum is shown by the dashed line. It can be seen that in the worst case the activity has decayed to only 40 percent of maximum 7 days after the mainshock. Thus, whatever the maximum daily activity (N_{max}) with which the storage capacity is designed to cope, we are required to be able to deal with $\sim 3.6 \ N_{max}$ events during the first 5 days, and $\sim 5.4 \ N_{max}$ during the first 10 days of such a mainshock-aftershock series.

We are left with the question of a reasonable upper bound to the number of events the SDMS can be expected to handle. Table I-2 lists the number of occurrences of earthquake sequences generating initial daily activity at 3, 4, 5, and 10 times the average rate for the PDE event list. Sequences of twice the average daily activity occur very frequently (less than monthly), and it seems reasonable to expect the SDMS to handle earthquake sequences involving initial daily rates of 3 to 4 times the average activity. To cope with the slower rate of decay of activity from the initial maximum of such sequences, we therefore require sufficient storage and computational capacity to be able to cope with 10 to 15 times the average activity over the 5-day interval suggested as a suitable delay between data receipt and bulletin publication, or an ability to handle 2 to 3 times average daily event occurrence. The system will, of course, be overloaded by the very active sequences occurring at intervals of a year or more.

It should be noted that the major effect of large increases in activity will be upon analyst manpower and computational requirements. The total volume of real-time data will, of course, remain constant: what will be severely taxed are waveform detection (automatic and manual) and association. It is quite likely that the computer time required for the association scheme will

CCURRENCE RAT	TABLE 1-2 TE OF AFTERSHOCK SEQUENCES	OF A GIVEN ACTIVIT
Average Activity x	No. of Event Sequences Exceeding This Activity (1964–1977)	Average Interval
3	34	~5 months
4	16	~10 months
5	9	~1.5 years
10	3	~5 years

increase nonlinearly with the rate of incoming arrival-time data. We propose to examine in detail the relationship between association time and input arrival data rates.

R.G. North

E. COMPUTATIONAL REQUIREMENTS FOR SDMS DETECTION ALGORITHM

Under the current design, the SDMS is required to collect and analyze seismic data from up to 52 nine-channel seismic stations. In order to reduce the amount of data that must be observed by seismic analysts, a detection algorithm will scan the data and identify portions of the data which warrant further investigation by an analyst. The following is an estimate of the computational requirements of several possible detection algorithms.

The requirements of the detection algorithm appear to be:

- R2 Although the algorithm need not run in real time, its implementation must be fast enough to catch up if data processing gets behind schedule.
- R3 The detector will operate on a single channel of data, or at least on a single station. There will be no array beam forming or using information from other stations at the detector level.
- R4 Monitor the data channels and report any that are not operating properly.
- R5 The detector must be capable of detecting local, regional, and teleseismic signals at reasonable false-alarm rates.
- R6 Report the time of arrival of a signal and possibly several other parameters, such as duration and amplitude. The detector will be primarily a "first pass" over the data, and its description of the detection will be intentionally crude. The arrival time may only be accurate to several seconds. Further automatic processing before the data are viewed by an analyst will not be considered here, but is not ruled out.

The computational requirements of five detection algorithms (referred to as STRAW, POLARIZATION, FRASIER, FFT, and PREDICTION) were investigated and their requirements are summarized in Table I-3.

	TABLE		
PPROXIMATE NUMB	ER OF MULT REQUIRED PER		ADDITION
Method	Per Point	Per LSTA Point	Per Second
STRAW	13	18	144
POLARIZATION	35	150	1640
FRASIER	128	0	2816
FFT	0	640	600
Prediction	60	0	2640

The STRAW detector is similar to the more traditional power-law detectors currently used to detect seismic signals. It was designed to be of minimum complexity in order to set a lower bound on the number of operations required per second. The STRAW algorithm computes a z-statistic of the short-term signal power and whenever this statistic exceeds a threshold value, a trigger is declared. The z-statistic requires estimating the background noise level, and care is taken so that this estimate will not be contaminated by an actual seismic signal. The STRAW detector also monitors the station to make sure that it is operating properly. The other detectors are variations of the STRAW detector, where more sophisticated processing replaces the power-law detector.

The POLARIZATION detector capitalizes on the fact that, in theory, body waves are linearly polarized (rectilinear) and that seismic noise is often elliptically polarized. A polarization filter uses 3 components of data to emphasize those portions of the data which are rectilinear.

The FRASIER and FFT detectors are both multiband detectors for which the input data are filtered into a number of narrow-frequency bands and a detection can occur on any band. The FRASIER detector uses a simple recursive relation to filter the data. The FFT detector uses the fast Fourier transform to filter the data. When a large number of filters are used, the FFT detector is more efficient than the FRASIER detector.

The PREDICTION detector uses a prediction-error filter to predict the noise at a future time, and subtracts the prediction from the data actually present at that time. Since the filter does not predict a seismic signal, a significant prediction error indicates a signal. The prediction-error filter used is an adaptive one used by McCowan.

A summary of the number of multiplications followed by additions required by the different detection algorithms is shown in Table I-3. The computation can be divided into the number of operations required per data point and those required every LSTA point, where LSTA is the length of the short term window (a 3-sec window was assumed). The requirements of the multiband detectors depend on the number of frequency bands. For this many frequency bands, the FFT approach is clearly cheaper than Frasier's. The prediction detector depends on the length of the prediction-error operator, and a length of 20 is assumed.

The more sophisticated detectors require between 4 and 20 times the computer power than the straw detection algorithm. Whether this additional cost is worth it or not will have to be established experimentally.

Although the advanced detectors are attractive, they do bring with them some possible problems. First of all, multidimensional pattern-recognition problems are usually harder than lower-dimensional ones, and they can be hard to optimize to provide the best detection capability. Also, "seismic intuition" can be lost once the data have been extensively transformed.

Both the polarization detector and the prediction-error detector are potentially more powerful than the power-law detector because they use more a priori knowledge about the signals they are trying to detect. On the other hand, their model of the signal is more restrictive than that of the power-law detector. For example, the polarization detector assumes that seismic signals are polarized. In reality, much of the energy of the coda of a seismogram is not obviously polarized and thus the power-law detector may do better than the polarization detector for weak events.

Although the advanced methods have been shown to be quite effective, they have never been used in a completely automatic environment; they seem to require some human guidance to be used effectively. It may be that the most effective use of these techniques is to refine the arrival time once a simple detector has detected it.

K.R. Anderson

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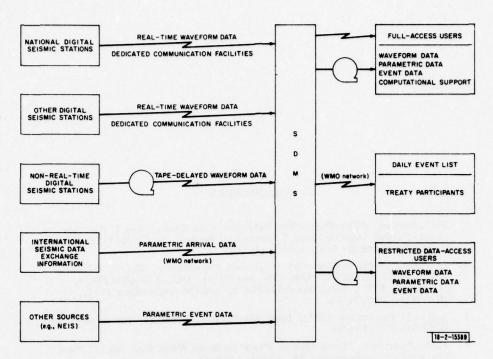


Fig. I-1. SDMS projected external data flow.

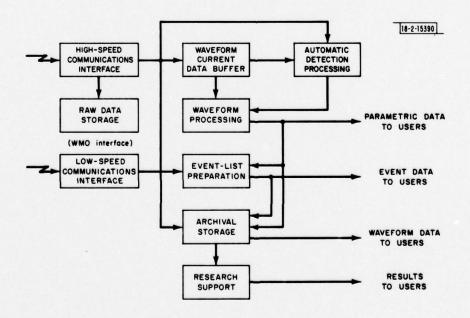


Fig. I-2. Functional organization of SDMS.

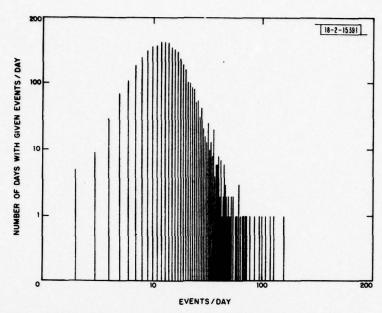
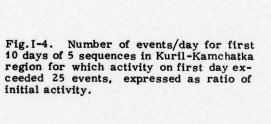
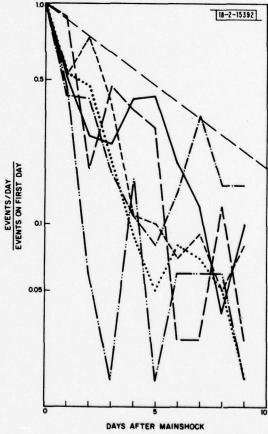


Fig.I-3. Histogram of occurrences of particular numbers of events/day, from PDE Bulletin for 1964-1977. Note logarithmic scales.





II. LOCATIONS AND TRAVEL TIMES

A. RESULTS OF A MASTER-EVENT LOCATION EXPERIMENT USING A LIMITED NUMBER OF NEAR-REGIONAL STATIONS

An experiment was conducted to determine the improvement of the epicenter locations for three NTS shots by the addition of crustal-phase detections from a limited number of stations less than 10° from the source. In this experiment, the three NTS shots used were REX (m_b 5.0), COMMODORE (m_b 5.8), and BOXCAR (m_b 6.2); and the seven near-regional stations used were Mn-, Kn-, PAS, DUG, MIN, TUC, and BMO.

A master-event method was incorporated in the relocating of these events. Initially, no improvement in the epicenter location of events COMMODORE and BOXCAR was observed after adding the seven stations' crustal phase to the teleseismic detections, but substantial improvement in the epicenter location of REX was observed after these detections were added. This difference was attributed to the large number of teleseismic detections used in the location of COMMODORE and BOXCAR (≈150 each), while only sixteen teleseismic detections were used in locating event REX.

We attempted to simulate the size of event REX for events COMMODORE and BOXCAR by limiting the distance of the teleseismic stations to be less than 30° from the source before using the detections in the relocations. This made a much better comparison between the number of teleseismic detections used in relocating COMMODORE (23), BOXCAR (22), and the number used in relocating REX (16). The fallacy of this method of event size reduction is that the quality of the time picks due to the better signal-to-noise ratio (S/N) is not taken into account.

The results of relocating the epicenters using the master-event method for event REX, and the simulated events COMMODORE and BOXCAR using the additions of crustal phases from one to seven near-regional stations, are listed in Tables II-1, II-2, and II-3.

A general conclusion of this experiment is that location accuracy is enhanced by adding near-regional crustal phases for small events when only a limited number of teleseismic station detectors are available. In particular, the mislocation error for event REX was decreased by adding only one near-regional detection, while this error for event COMMODORE was decreased only when four or more near-regional detections were added to the teleseismic detections. The mislocation errors for event BOXCAR do not show the linear decrease that appears for event REX, but this is probably due to a small timing error (less than ±1.0 sec) for either station Mn-, Kn-, or PAS. If the above assumption is true, improvement in the mislocation error is decreased with the addition of three or more near-regional detections.

R. E. Needham D. W. McCowan

B. NTS SHOT LOCATIONS RELATIVE TO A MASTER

Nonrandom as well as random errors in computed earthquake and shot locations can be investigated if accurate locations are known a priori. Errors in computed focal depths are expected to be greater than the corresponding errors in epicenters, and actual locations generally lie outside the 95-percent confidence limits for the computed locations. For example, Fitch presented evidence for nonrandom errors of 25 km in the focal depths reported in the Bulletins of the International Seismic Center (ISC) for shallow earthquakes in the Kuril region. The corresponding standard errors in focal depth were less than 10 km. These results pertain to the well-recorded earthquakes.

RESULTS	OF THE REX MA	TABLE 11-1 RESULTS OF THE REX MASTER-EVENT RELOCATION EXPERIMENT USING LIMITED NUMBER OF NEAR-REGIONAL STATIONS	OCATION SIONAL S	EXPERIMENT TATIONS		
	Latitude (°N)	Longitude (°W)	Depth (km)	Confidence Ellipse Area (km ²)	Mislocation (km)	Number of Observations
REX Hypocenter	37.27	116.43	0.672	1	1	
Corrected Greeley Common Data $\Delta \geqslant 10.0$ Res $\geqslant -1.0, \leqslant 1.0$	37.18 ± 0.08	116.44 ± 0.1	1.06	252.48	10.0	91
Corrected Greeley Common Data Δ≥ 10.0 Res > -1.0, <1.0 +Mn-, Kn-, PAS, DUG, MIN, TUC, BMO	37.22 ± 0.03	116.43 ± 0.05	9.0	42.89	5.6	*
Corrected Greeley Common Data Δ≥ 10.0 Res > -1.0, <1.0 +Kn-, PAS, DUG, MIN, TUC, BMO	37.22 ± 0.03	116.42 ± 0.05	1.06	8.4.8	5.6	Z
Corrected Greeley Common Data ∆≥ 10.0 Res ≥ -1.0, <1.0 +PAS, DUG, MIN, TUC, BMO	37.22 ± 0.03	116.43 ± 0.05	9.1	56.34	5.6	. 23
Corrected Greeley Common Data Δ≥ 10.0 Res ≥ -1.0, <1.0 +DUG, MIN, TUC, BMO	37.22 ± 0.03	116.46 ± 0.06	98.1	Z.06	6.2	20
Corrected Greeley Common Data △ > 10.0 Res > -1.0, <1.0 +MIN, TUC, BMO	37.20 ± 0.05	116,45 ± 0.08	9.1	105.29	8.0	<u>&</u>
Corrected Greeley Common Data △ > 10.0 Res > -1.0, <1.0 +TUC, BMO	37.21 ± 0.06	116.43 ± 0.1	9.1	159.67	6.7	81
Corrected Greeley Common Data $\Delta \geqslant 10.0 \text{ Res } \geqslant -1.0, \leqslant 1.0$ +BMO	37.20 ±.0.08	116.43 ± 0.1	1.06	234.97	7.8	71

RESULTS OF USIN	THE COMMODE	TABLE 11–2 RESULTS OF THE COMMODORE MASTER-EVENT RELOCATION EXPERIMENT USING LIMITED NUMBER OF NEAR-REGIONAL STATIONS	AT RELOC.	ATION EXPERIA	AENT	
	Latitude (°N)	Longitude (°W)	Depth (km)	Confidence Ellipse Area (km ²)	Mislocation (km)	Number of Observations
COMMODORE Hypocenter	37.13	116.06	0.746	1	ı	F
Corrected Greeley Common Data $\Delta \geqslant 10.0$ Res $\geqslant -1.0, \leqslant 1.0$	37.18 ± 0.05	116.03 ± 0.08	1.06	87.73	6.2	6
Corrected Greeley Common Data $\Delta \geqslant 10.0 \text{ Res} \geqslant -1.0, \leqslant 1.0 + \text{Mn-, Kn-, PAS, DUG, MIN, BMO}$	37.15 ± 0.03	116,10 ± 0.03	1.06	27.89	4.5	78
Corrected Greeley Common Data $\Delta \geqslant 10.0 \text{ Res } \geqslant -1.0, \leqslant 1.0 + Kn-, PAS, DUG, MIN, BMO$	37.15 ± 0.03	116.10 ± 0.04	1.00	30.32	4.2	56
Corrected Greeley Common Data ∆≥ 10.0 Res ≥ -1.0, < 1.0 +PAS, DUG, MIN, BMO	37.15 ± 0.03	116.06 ± 0.04	1.06	36.68	2.2	24
Corrected Greeley Common Data $\Delta \geqslant 10.0 \text{ Res } \geqslant -1.0, \leqslant 1.0 + \text{DUG}, \text{ MIN, BMO}$	37.18 ± 0.04	116.03 ± 0.05	1.0G	55.89	6.2	23

RESULTS	OF BOXCAR MG LIMITED NUN	TABLE 11-3 RESULTS OF BOXCAR MASTER-EVENT RELOCATION EXPERIMENT USING LIMITED NUMBER OF NEAR-REGIONAL STATIONS	OCATION GIONAL	EXPERIMENT STATIONS		
	Latitude (°N)	Longitude (*W)	Depth (km)	Confidence Depth Area (km ²)	Mislocation (km)	Number of Observations
BOXCAR Hypocenter	37.30	116.46	1.16	1	1	1
Corrected Greeley Common Data △ > 10.0 Res > -1.0, < 1.0	37.30 ± 0.05	116.44 ± 0.07	1.06	82.89	1.8	22
Corrected Greeley Common Data \$\triangle 10.0 \text{Res} > -1.0, \left 1.0 \\ +Mn^{-}, \text{Kn}^{-}, \text{PAS}, \text{DUG}, \text{MIN}, \text{TUC}, \text{BMO}	37.27 ± 0.03	116.47 ± 0.04	1.06	29.01	3.5	E
Corrected Greeley Common Data \$\triangle \text{10.0 Res} > -1.0, \in 1.0 \\ +Kn-, PAS, DUG, MIN, TUC, BMO	37.27 ± 0.03	116.47 ± 0.04	1.00	31.55	3.5	&
Corrected Greeley Common Data Δ≥ 10.0 Res ≥ -1.0, < 1.0 +PAS, DUG, MIN, TUC, BMO	37.27 ± 0.03	116.47 ± 0.04	1.06	33.02	3.5	
Corrected Greeley Common Data \$\triangle \gamma \gamma \qq 10.0 \text{ Res } \gamma -1.0, \le 1.0 +DUG, MIN, TUC, BMO	37.29 ± 0.04	116,46 ± 0.05	9.1	49.15	2	8
Corrected Greeley Common Data $\Delta \geqslant 10.0 \text{ Res } \geqslant -1.0, \leqslant 1.0 + MiN, TUC, BMO$	37.29 ± 0.05	116,45 ± 0.05	1.06	53.21	4.	প্ন
Corrected Greeley Common Data \$\triangle > 10.0 Res > -1.0, \le 1.0 +TUC, BMO	37.29 ± 0.05	116.44 ± 0.07	90.1	64.67	2.1	25
Corrected Greeley Common Data △ > 10.0 Res > -1.0, < 1.0 +BMO	37.30 ± 0.05	116.44 ± 0.07	50.1	65.97	1.8	23

Twenty NTS shots and one earthquake were located relative to the shot on 20 November 1975. The relative-location procedure has been described previously by Fitch and Jackson and Jackson and Fitch. Relative locations are more precise than ISC locations because of a diminished dependence on uncalibrated travel times. The shots chosen for relative locations had more than 100 P and PKP times reported to the ISC in the years 1971 to 1973. These data were retrieved from a disk file of all ISC data from the years 1964 through 1975. The formatting of the disk file was done by Adam Dziewonski.

Relative epicenters in Fig. II-1 can be compared with epicenters for the shots and the ISC epicenter for the earthquake in Fig. II-2. Error bars represent one standard deviation. The lack of local ($\Delta < 5^{\circ}$) and near-regional stations ($5^{\circ} < \Delta < 25^{\circ}$) toward the south accounts for the longer N-S error bars. There is general agreement between the computed and actual epicenters for the shots within 95-percent confidence limits given by twice the error bars shown in Fig. II-1. The relative epicenter for the earthquake suggests that its correct location is closer to the cluster of shots near the SE corner of the test site than the ISC location would suggest.

Figure II-3 shows that relative focal depths for shots near the master have an average systematic error of approximately ±2 km. Shots clustered SE of the master show an average systematic error of approximately ±5 km in relative focal depth. Random errors in relative focal depth are about ±5 km at the level of one standard deviation. The corresponding ISC focal depths are approximately 10 ± 5 km. Consequently, relative depths have no more than one-half the systematic error of ISC depths for this activity. It is worth noting that the relative depth of the earthquakes is, with one exception, below the relative depths of the shots in the SE cluster. This suggests that its focal depth is greater than the shots by about 5 km. From the results of this study, it is apparent that, even if the systematic errors are significantly reduced by the use of calibrated travel times, earthquakes within 10 km of the surface will be difficult to distinguish from shots on the basis of computed focal depths.

T. J. Fitch

C. DISTRIBUTION OF LOCATION INFORMATION FROM ARRIVAL TIMES

In a linear problem of the form

$$V^{-1/2}Ax = V^{-1/2}b {(II-1)}$$

the importance of each datum (represented by components of the vector b) in the solution for the model (represented by the vector x) is given by the matrix describing how well the model predicts the data. In Eq. (II-1), V and A are the diagonal matrix of data-variance estimates and the coefficient matrix, respectively. Substitution of the least-squares solution to Eq. (II-1):

$$x = (A^{+}V^{-1}A)^{-1} A^{+}V^{-1}b$$
 (II-2)

back into Eq. (II-1) yields the information matrix:

$$V^{1/2}A(A^{\dagger}V^{-1}A)^{-1}A^{\dagger}V^{-1/2}$$
 (II-3)

Importance is defined by the diagonal elements of the information matrix, by Minster et al.³

A datum that provides independent information for the solution has an importance of one, and the sum of importances equals the number of model parameters. In the case of earthquake locations, there are four model parameters, and Eq. (II-1) represents a linearized form of a nonlinear equation with travel-time residuals as components of the data vector.

The importance of differential travel-time residuals in relative locations of NTS shots (see Sec. B above) is distributed in the following way with respect to epicentral distance: the accumulated importance of local stations, $\Delta < 5^{\circ}$, is 0.6; that for near-regional stations, $5^{\circ} < \Delta < 25^{\circ}$, is 1.4; and the remaining one-half of the total importance of four is distributed among the teleseismic stations. Removing the local stations from the data set raises the accumulated importance of the near-regional stations to 2.0 and does not greatly degrade the relative locations. This is a consequence of the projection of ray paths to the local and near-regional stations onto a narrow band on the focal sphere. In Fig. II-4 these ray paths define the outer rite of data points corresponding to take-off angles close to 38° (measured from the downward vertical). This distribution of ray paths results from the assumption of a 5.0-km/sec compression velocity for the crust beneath the test site. As more stations are removed from the data set, the distribution of importances becomes less uniform with azimuth and distance. Eventually, a small subset of the total data set will provide essentially all the information for the location. In this case, locations might be substantially moved by rereading arrival times from the important stations.

T. J. Fitch

D. A METHOD FOR ESTIMATING RAYLEIGH-WAVE GROUP TRAVEL TIMES

A program has been written based on a method due to Mauk⁴ for estimating the Rayleighwave group travel time between any two points on the globe. Basically, the method consists of dividing the globe into 5° by 5° latitude-longitude squares which have been marked for their relative content of 20 tectonic structures. This contrasts with the scheme which Filson⁵ developed for the ISM, where he used 15° by 15° squares and 3 tectonic structures. Once the tectonic composition of the path between the two points on the globe is known, the group travel time can be expressed as the sum of the group delays in each of the component structures at whatever period is desired. The present version of the program allows nine equally spaced periods between 20 and 100 sec.

As an example of how the program works, we present some calculations on a $\pm 40 \times \pm 40$ latitude-longitude grid centered on the Mashad SRO site. The two plots shown in Figs. II-5 and II-6 are contours of group travel time, at a 20- and 40-sec period respectively, from points on the grid to Mashad. The figures show that, at both periods, there is substantial asymmetry in the contours, with the group travel times increasing most rapidly in the north-south direction. Furthermore, the 20-sec plot (Fig. II-5) shows an anomalously low group-travel-time area about 28° directly south of Mashad. This corresponds to the Arabian Basin part of the Indian Ocean, where one would expect low group velocities.

To show the variation in group velocity that the method allows, a plot of average group velocity at a 100-sec period is shown in Fig. II-7. This plot is on the same grid as were the previous two plots. Here, even at a 100-sec period, the program is able to produce an elaborate group-velocity pattern. This amount of detail, coupled with the ease the Mauk gridwork scheme can be updated or changed, should help us estimate more accurate group travel times to aid in identifying surface wavetrains.

D. W. McCowan A. M. Dziewonski

E. STATION ANOMALIES FOR P-WAVE TRAVEL TIMES

Lateral heterogeneities in the earth's structure can lead to significant errors in estimation of the parameters of a seismic source. Ideally, one would like to determine the three-dimensional velocity distribution and give a full account of deviations of the ray paths and travel times from those corresponding to a spherically symmetric model. It is clear, however, that this goal is not attainable in the foreseeable future. Another, more pragmatic approach is to calibrate the earth by determining empirically the travel times between each source and each receiver; in essence, this is the philosophy of the "master event" technique. This method, especially well suited for relative location of events within a particular source region, has been successfully used for some time, although on a rather limited scale.

A rather simple partial calibration can be achieved by evaluating the pattern of deviations from the global average at a receiver site. Station corrections have been published by Cleary and Hales, Herrin and Taggart, Lilwall and Douglas, and Sengupta and Julian. The methods used, and the size and quality of the data sets were different in all these studies, yet it is clear that there is very significant correlation between the azimuth-independent terms. These studies have also demonstrated a correspondence between the values of corrections and the tectonic nature of the station sites. Terms dependent on azimuth were also published in Refs. 7 and 8, but Sengupta and Julian found no significant correlation between these two sets of results. It is also rather clear from Fig. 3 of Herrin and Taggart that their azimuthal terms show no significant regional correlation. This negative outcome of the attempt to isolate azimuth-dependent terms has been most likely caused by the lack of a sufficiently large set of observations.

In this study, the data on P-wave arrival times contained in the Bulletin of the International Seismological Center (ISC) for the years 1964-1975 were used to derive an improved set of travel times and to investigate station residuals. Two curves representing deviations from the Jeffreys-Bullen (J-B) tables for surface focus are shown in Fig. II-8. The curve labeled "Direct Average" represents the result of averaging in 1° cells all available data for earthquakes with at least 30 first-arrival readings. One could suspect a bias in this curve due to uneven distribution of stations and receivers. The set labeled "Azimuthal Average" has been obtained by establishing 20 equal-azimuth windows and averaging the travel times for each window separately. The results shown were derived by averaging with equal weight all 20 travel-time curves. Both sets are practically identical up to a distance of 85°; at greater distances, the differences are as large as 0.2 sec. The set obtained by azimuthal averaging may be considered to reflect better the global properties of the Earth and has been applied in the next step of the analysis.

After smoothing by cubic spines, the improved travel-time curve was used to relocate 4536 events with at least 30 arrivals in the distance range from 25° to 100° and at least four stations in each quadrant. The recomputed travel-time curve showed only minor changes—maximum perturbations did not exceed 0.1 sec and it seemed pointless to continue the iterative process.

The residuals for the 4536-event data set with respect to this final travel-time curve were sorted according to stations, and these data have been used to investigate the receiver anomalies. These anomalies clearly represent contributions of the heterogeneities near the source and receiver regions as well as those in the deep mantle; Romanowicz 11 proposed to calibrate the earth by averaging the residuals in properly selected azimuth-distance cells. However, with

very few exceptions, the number of data is inadequate to obtain reliable averages for sufficiently small cells that would reflect the fine effects of subducted slabs, for example. In this study, it appeared more important to investigate the overall spatial coherence of the station residuals. Stations with fewer than 50 residuals were eliminated from further analysis. The full range of azimuth was discretized into 18 windows. An average residual was computed for each window if it contained four or more readings. The azimuthal dependence was assumed to have the following form:

$$\delta t = A_0 + A_1 \cos Az + B_1 \sin Az + A_2 \cos 2Az + B_2 \sin 2Az \quad .$$

The decisions on the number of terms in this expansion to be fitted to the data depended on the azimuthal coverage. Generally, for stations with data for less than 9 windows, only the A_0 term could be determined by simply averaging (with equal weight) the results for the individual windows. For stations with data for more than 13 windows, it was most often possible to obtain a reliable least-squares fit for all five terms. As a rule, terms A_0 , A_1 , and B_1 could be fitted for stations with the data from 9 to 13 windows. However, the decisions depended on the distribution of the missing windows, and choices were made on an individual basis using an interactive graphics terminal.

The results for 751 stations are listed in Table II-4; most of the entries are self-explanatory. The column RMS0 describes the standard deviation for an individual window after the A_0 term has been removed; RMS1 is the standard deviation after correcting for the azimuthal terms (if any). Comparison of these two numbers allows us to assess the improvement achieved by considering azimuthal dependence. The station correction terms correspond to the following representation:

$$\delta t = A_0 + A_1 \cos(Az - E_1) + A_2 \cos 2(Az - E_2)$$
;

thus, the angles E_1 and E_2 represent the "slowest" directions for the appropriate azimuthal terms.

Figure II-9 shows the results for station Kizyl-Arvat in the USSR, which has one of the largest azimuthal terms ($A_1 = 1.56$ sec) among the stations with good azimuthal coverage. The rms error decreases from 1.08 to 0.21 sec after the azimuth-dependent terms are taken into account.

The question of spatial coherence is examined in Figs. II-10 through II-13. Figure II-10 shows residuals for stations NTI and NEW that are only 40 km apart; clearly, the anomalies are nearly identical at both stations. Nearly equally good correlation exists between stations VIC and LON separated by approximately 250 km (see Fig. II-11). Great similarity can also be observed between residuals at BMO and FHC, shown in Fig. II-12, despite the fact that they are more than 500 km apart. All three figures show substantial similarities, even though they refer to stations between 40.80°N and 48.52°N and from 116.97°W to 123.99°W. For these as well as several other stations in this area, a particular consistency is noted among the phases of the two azimuthal terms. This might lead one to speculate that these two terms may be due to different causes. However, it is possible that in the examples shown so far, the azimuthal variation could be due to the source or lower-mantle effects. Such an explanation is not likely in the case of stations EDM and SES shown in Fig. II-13. Even though those stations are separated by only slightly more than 300 km, the pattern of their residuals is entirely different – while Edmonton has a large (A₁ = 0.7 sec) azimuthal term, there is practically no azimuthal dependence

TABLE II-4

CORRECTIONS TO P-WAVE TRAVEL TIMES FOR 751 STATIONS [Correction term is to be evaluated according to following formula: $\delta t = A_0 + A_1 \cos{(Az - E_1)} + A_2 \cos{2(Az - E_2)}$. Angles E_1 and E_2 thus indicate the azimuth corresponding to the slowest travel times for a particular term. Further details can be found in the text.]

							211 410				
St	ation	_								-	
Code Lat	. Long. Ele	v. NORS	NW	RMS0	RMS1	A ₀	A ₁	E	A ₂	E2	
			_				-	_			1111
AAB 43.267			18	0.62	0.24	0.26		89	0.33		
AAE 9.029			16	0.46	0.43	2.03	0.19		0.08		
AAM 42.300			11	0.41	0.35	-0.02	0.25		0.12	113	
	3 -106.458 184			0.33	0.28	0.37	0.30				
ABU 34.859	135.573 20	0 706	12	0.38	0.34	0.30	0.24	148			
											754
		1 67		0.15		0.27					Un- and
	7 138.709 65			0.46		0.24			0.21		
	1 -176.685 1			0.72			0.41				
	-171.777 70		15	0.50	0.40	0.21	0.24				
AFR -17.538	3 -149.778	0 515	14	0.74	0.61	0.27	0.49	344	0.60	115	
AIA -65.250		1 180	7	0.24	0.17	-0.21	0.25	27			
AKU 65.687	7 -18.107 2	4 624		0.47	0.35	1.50	0.36	133	0.32	138	
		5 227	9	0.62		0.60					
ALE 82.48		5 2098			0.30	-0.58	0.48	35	0.31	111	
ALG 36.772	and the second s	9 203	12	0.51	0.50	-0.01	0.18				
ALI 38.355	-0.487	5 295	15	0.52	0.46	0.66	0.33	5	0.07	114	
ALM 36.85		5 279	14	0.63	0.55	0.50	0.50				
	-106.458 185			0.40	0.35	0.19	0.18	29	0.23	116	
ALT 39.05			6	0.63	3.33	-0.09		-,	33		
ANG 17.155		3 96		0.49	0.28	-0.00	0.68	79			
2	2030	, ,,,		3.73	7.20	0.00	3.00	,,			
ANK 39.917	32.817	0 294	8	0.54		0.10					
ANR 39.91 ANP 25.183				0.63	0.38	1.36	0 65	300	0.34	121	
ANR 40.755				0.03	0.30	0.53	0.05				2 1 2 4
ANT -23.699		0 198			0.36	-0.13					
APA 67.550	33.333 11	0 1678	18	0.58	0.35	0.09	0.64	229	0.16	/1	
400 (0.51	13 000	h 0-	_	0 110		0 -0					
APP 60.54			7	0.48		-0.58					
		3 85		0.62		0.47		~~		70	
AQU 42.354				0.60	0.39	0.02	0.70	28	0.15	78	
		9 70		0.21		1.14					
ARE -16.462	2 -71.491 245	2 439	16	0.68	0.36	-0.23	0.78	223	0.35	108	
ARG 36.216			12	0.45	0.18	-0.37	0.51			61	
ARH 45.010				0.32	0.28	0.37	0.20	63	0.07	44	
ART 11.52				0.39		1.34					
ASH 37.950				0.38	0.30	0.68			0.30		
ASP -23.683	3 133.897 60	0 1573	17	0.37	0.28	-0.75	0.31	305	0.21	55	
	7 -111.933 35		7	0.54		0.68					
ATH 37.972		5 1062		0.67	0.35	-0.12	0.64	209	0.45	142	
ATL 33.433	3 -84.337 27	2 160	5	0.74		-0.48					
AVE 33.29				0.47	0.34	0.15	0.45	200	0.05	35	
BAA -34.59		5 72		0.69		0.65					
BAB 30.12	1 -2.186	0 383	15	0.38	0.29	-0.31	0.29	174	0.16	31	
BAC 46.56			15	-	0.47	0.42	0.39		0.87		
BAE -15.84						-0.33		88			
BAF 47.83				0.52		-0.23					
BAG 16.41				0.67	0.36	-0.19	0.71	244	0.38	122	
					3.30	,	3.11				
BAK 40.38	49.900 -	2 379	10	0.46	0.23	2.59	0.60	173			
	2 -115.558 140	0 125		0.65	0.23	-0.48	3.00	.,,			
BAO -15.635				0.41		-0.48					
BAS 47.540					0.51	0.34	0.11	206			
BCK 37.460				0.38	0.51	-0.30					
3,77,00	-						_				

		de la seconda		TABLE	11-4	(Cont	inued)						
	Stat	tion			1					_		-	
Code	Lat.	Long.	Elev.	NOBS	NW	RMS0	RMS1	A ₀	<u>A</u> 1	<u>E</u> 1	A2	E ₂	
BCN		-114.834	776	714	16	0.36	0.26	0.65	0.31	14	0.16	6	
BCR BDB	7.019	-73.176 0.148	750 561	83 221	6	0.83	0.24	-1.64	0.07	295			
	-15.664	-47.903		137	9	0.47	0.41	-0.36	0.35				
BEC	32.379	-64.681	41	106	4	1.10		0.31					
BEO	44.821	20.455	129	371	11	0.38	0.30	0.74	0.07	1	0.36		
BER	60.387	5.326	22	1031	17	0.49	0.35	0.46	0.26		0.40	-	
BES BFD	47.250 -37.176	5.987 142.544	311 235	508 768	14	0.35	0.26	0.24	0.33		0.27	122	
BGO	41.378	-83.659	212	158	8	0.46	0.35	-0.33	0.55	77	0.55	123	
BHA -	-14.447	28.468		1093	18	0.78	0.50	-0.41	0.66	321	0.53	71	
BHP	31.417 8.961	76.417	410 36	205 145	7	0.20	0.49	-0.01 -0.19	0.93	00			
BIG		-155.217	562	335	12	0.64	0.49	-0.19			0.15	102	
BIZ	45.939	26.104	410	59	4	1.91		-1.16		,,			
BKR	41.733	43.517	1500	1943	17	0.30	0.19	0.72	0.32	63	0.15	148	
BKS		-122.235	276	1525	16	0.30	0.24	0.79	0.21	61	0.10	34	
BLA	37.211	-80.421	634	402	15	0.42	0.21	0.19	0.51	93	0.15	11	
BLC	64.317		16	1686	17	0.36	0.30	-1.01	0.16		0.24	82	
BLF -	-29.109	26.188	1420	238	12	0.49	0.37	0.25	0.40	81			
BLO	39.172		230	69	2	0.08		-1.17					
BLR		-145.845	792	678	14	0.27	0.12	-0.16	0.07	2	0.37	59	
BMN	40.431	-117.222	1505	345	13	0.34	0.15	0.51	0.34		0.23		
BMO BNG	4.367	-117.306 18.567	378	2497 1031	16 17	0.42	0.21	-0.55 -1.25	0.32		0.41	84	
BNH	44.591	-71.256	472	389	11	0.30	0.17	0.47	0.31		0.11	55	
BNS BOD	50.964	7.176 114.183	200 250	1274 2360	16 18	0.28	0.25	0.26	0.13		0.12	89 37	
BOG	4.623	-74.065	2658	441	15	0.66	0.38	1.21	0.69		0.46	43	
вок	23.783	85.883	298	413	11	0.45	0.32	0.53	0.40		0.40	13	
BOL	44.487	11.329	80	63	5	1.06		1.01					
BOM	18.900	72.817	0	388	8	0.43		-0.26					
BOU		-105.271		126	5	0.38		0.83					
BOZ		-111.633		460	14	0.21	0.19	-0.09	0.13	252	0.02	34	
BPT		-73.242	83	78	7	0.45		0.01					
BRA	48.168	17.105	270	1263	17	0.49	0.32	-0.19	0.44	356	0.26	41	
BRG	50.874	13.946	296	836	15	0.26	0.20	-0.08	0.16	357	0.23	101	
BRK		-122.260	81	79	5	0.36		0.35					
BRL BRN	52.464	13.301 13.203	50 45	87 122	6	0.61		0.97					
					'			0.93					
	-27.392	152.775		2187	17	0.64	0.59	-0.14			0.36		
BRW		-156.748	1200	954	15	0.52	0.37	0.37			0.41		
BSF BTR	47.833 -2.617	6.794	0.000	747 88	15	0.22	0.16	-0.03 0.60	0.05	308	0.22	169	
BUB	47.749	8.603	740	309	11	0.52	0.35	-0.91	0.70	344			
BUC	44.414	26.097	82	770	15	0.51	0.28	0.61	0.55	156	0.14	132	
BUD	47.484	19.024	196	693	15	0.48	0.39	0.61	0.17		0.33		
BUH	48.676	8.228	750	1012	16	0.40	0.30	-0.29	0.25	331	0.26	173	
	-20.143	28.613		1766	18	0.63	0.53	-0.72	0.36	17	0.32	99	
BUT	40.013	-112.563	1758	658	16	0.25	0.24	0.16	0.06	161	0.08	20	

TABLE 11-4 (Continued) Station <u>A</u>1 $\frac{E_1}{2}$ A₀ Code Long. Elev. NOBS NW RMS0 RMS1 Lat. BY1 -80.005 -119.043 1449 253 0.74 0.04 BYR -80.017 -119.517 1515 390 0.62 0.51 0.25 0.63 187 CAL 22.535 88.367 165 9 0.34 0.32 2.14 0.17 250 18 0.39 CAN -35.321 148.999 700 2684 0.37 0.13 0.31 0.11 93 CAR 10.507 -66.927 1032 16 0.56 701 0.29 -0.54 0.65 39 0.27 CBM 46.932 -68.121 7 0.44 0.17 0.14 0.62 116 175 CBZ -52.560 169.159 65 6 30 0.33 1.29 CDF 48.394 7.271 1100 751 0.21 15 0.32 0.08 305 0.32 166 0.17 43.675 CDR 5.767 368 103 7 0.60 0.28 CED 34.277 -117.334 1067 73 6 0.53 0.45 CEN 13 0.72 0.64 -31.576 -68.754 180 -0.35 0.47 315 900 CER -33.362 19.295 472 84 6 0.63 1.04 CFF 45.763 3.102 400 144 8 0.46 0.46 0.44 0.04 CHA 10 0.49 26.833 87.167 161 338 0.44 -0.01 0.29 111 149 CHC 35.917 -79.050 148 6 0.60 0.72 CHG 18.790 98.977 416 1278 18 0.76 0.49 -0.65 0.76 129 0.29 120 CHI 41.900 -87.633 183 150 6 0.87 -0.58 CHN 4.967 -75.617 1360 166 9 0.95 0.80 -0.27 0.71 272 91.817 CHT 22.350 476 12 0.79 175 0.39 35 0.61 0.29 1.40 28.087 CIN 37.600 977 14 0.15 0.11 -0.47 0.11 66 0.04 43 CIR -21.013 31.580 430 1220 16 0.49 0.45 -0.07 0.08 266 0.27 8 CIZ -43.955 -176.566 45 96 5 0.63 1.33 CLE 41.489 -81.532 328 504 17 0.63 0.26 0.53 0.81 62 0.21 28 CLK -15.680 34.977 781 1080 16 0.57 0.34 239 0.11 79 0.50 -0.20 13.003 CLL 51.310 230 2101 17 0.21 0.13 -0.16 0.17 166 0.17 146 CLS 38.637 -122.585 457 82 4 0.30 0.41 CMC 67.833 -115.083 0.48 0.34 31 775 15 -0.46 0.05 263 0.50 41 25.038 CMP 45.268 16 0.67 0.69 0.84 359 0.14 141 598 1109 0.37 CNG -26.292 32.188 863 17 0.39 0.38 0.09 0.06 294 0.15 130 100 CNH 43.830 125.313 0 94 7 0.28 -0.63 CNN 39.137 -84.277 101 -0.93 203 3 0.29 0.45 CNT 23.092 113.338 0.57 77 5 CNU 30.660 104.012 0 91 6 0.55 -0.40 CNZ -39.200 175.547 1116 359 8 0.31 0.31 0.23 0.11 230 -41.088 COB 172.734 213 895 11 0.68 0.52 -0.14 0.68 268 COI 40.207 -8.418 140 52 4 0.27 0.41 0.30 64.900 -147.793 -0.51 0.81 4 0.16 158 COL 320 3057 16 0.64 -92.128 1528 -73.045 15 COM 16.253 180 7 0.43 0.79 -36.828 9 0.64 CON 100 -0.34 COO -30.578 151.892 653 220 7 0.39 1.09 COP 55.683 0.61 0.21 263 0.33 121 12.433 16 0.36 0.22 13 1129 44.586 -123.303 12 0.52 17 0.66 COR 123 290 0.41 0.81 0.52 359 CPO 35.595 -85.570 574 1226 0.28 -0.68 0.81 112 0.16 96 CPP -27.354 -70.351 384 67 3 0.36 -0.75 CRC 37.242 -122.130 87 5 0.46 0.87 CRT 37.190 -3.598 774 243 13 0.63 0.50 1.11 0.49 233 -34.432 172.680 278 0.58 CRZ 140 7 1.03 CSC 34.000 -81.033 94 130 5 0.42 -0.26 -20.088 146.254 0.28 -0.48 0.03 22 0.24 114 357 16 CTA 2246 0.33 0.65 0.26 62 CUM 10.465 -64.169 10 0.43 0.40 34 169

				TABLE	11-4	(Cont	inued)					
	Stat	ion										
Code	Lat.	Long.	Elev.	NOBS	<u>NW</u>	RMS0	RMS1	A ₀	<u>A</u> 1	$\frac{\mathbf{E_1}}{\mathbf{I}}$	A2	<u>E</u> 2
DAC		-117.594		342	13	0.40	0.28	0.77	0.18	57	0.32	
DAG	76.770	-18.770	16	654	16	0.44	0.21	-0.59	0.46		0.34	165
DAL	32.846	-96.784	187	170	8	0.30	0.24	0.11	0.27			
DAR	-12.408	130.818	6	774	11	0.63	0.63	-0.78				
DAV	7.088	125.575	85	1050	14	0.80	0.58	0.20	0.48	300	0.57	108
DBN	52.102	5.177	3	666	15	0.34	0.22	0.79	0.12	295	0.33	139
DBQ	42.507	-90.683	244	194	8	0.59	0.51	-0.65	0.48			
DCC	-10.510	25.455	1425	63	5	0.36		0.46				
DDI	30.322	78.056	682	566	12	0.60	0.48	0.31	0.47	316		
DDR	35.998	139.193	800	1695	14	0.42	0.23	0.02	0.41	62	0.51	98
DEV	45.883	22.903	195	450	12	0.27	0.23	0.40	0.20	129		
DIM	42.050	25.583	0	85	6	0.54		0.19	****	,		
DJA	-6.183	106.833	8	192	6	0.61		0.67				
DMK	41.822	27.757		408	9	0.24	0.19	-0.36	0.30	2		
DNP	-8.650	115.217	15	168	8	0.51	,	-0.05				
DOM	15 204	-61.391	15	66	7	0.22		-0 16				
DOU	15.296	4.594	15		7 17	0.22	0 29	-0.16	0 22	110	0.06	122
	50.096 39.581	28.637	225	1419	8		0.28		0.33	40	0.26	133
DRB		The second second	620	242		0.25	0 20	-0.15	0.01	262	0 15	28
DRV	-66.665	140.009	40	960	12	0.32	0.29	-0.56	0.04		0.15	28
DSH	38.558	68.775	847	2075	18	0.62	0.38	0.49	0.61	2/2	0.35	75
DUG		-112.813	1477	1714	17	0.30	0.19	0.31	0.02	217	0.31	159
DUN	-7.409	20.837	709	78	7	0.48		-0.68				
DUR	54.767	-1.583	103	836	16	0.48	0.40	0.63	0.03	306	0.36	126
EAB	56.188	-4.340	250	403	13	0.46	0.40	-0.38	0.38	337		
EAU	55.844	-3.455	350	402	13	0.29	0.25	-0.11	0.20	89		
EBH	56.248	-3.508	375	456	15	0.42	0.33	-0.16	0.15	272	0.33	15
EBL	55.773	-3.044	365	403	14	0.37	0.30	-0.21			0.13	
EBR	40.821	0.493	50	615	17	0.55	0.51	0.75	0.12		0.27	
EBS		-101.232	735	50	2	0.09		-0.17				
EDC	40.347	27.864	270	145	6	0.46		0.17				
EDI	55.923	-3.186	125	322	11	0.17	0.16	-0.13	0.09	28		
EDM		-113.350	730	2395	17			-0.50			0.17	61
EDU	56.547	-3.014		358	13	0.52	0.13	-0.28	0.24		0.17	01
EGL	55.862	-2.738	275 245			0.32	0.29					
		and the second s		463	13			-0.12	0.20		0 11	122
EIL	29.550	34.950	0	906	16	0.78	0.30	0.03	1.08	103	0.11	133
EKA	55.333	-3.159	300	1348	16	0.24	0.18	0.12	0.10	129	0.21	178
ELL	36.749			208	7	0.41		0.04				
ELO	56.471	-3.706	495	120	8	0.49		-0.37				
ELT	53.250	86.267					0.28	-0.72	0.07	298	0.32	159
ELY	39.131	-114.892	2011	61	6	0.23		0.54				
EMM	44.739	-67.489	20	118	6	0.43		0.11				
ERB		152.162		80		0.63		0.45				
ERE	40.183			171		0.52		0.47				
ERZ	39.915			473			0.32		0.69	336	0.38	120
ESA		150.814	46	953	11		0.15					
FOR	EE 217	-2 205	2112	001	16	0 22	0.33	0.21	0.07	17h	0.08	120
ESK ESM		-3.205 152 686		991	6	0.33	0.32		0.07	1/4	0.00	130
ETV		152.686 151.676		105 114		0.71		-0.40				
EUR		-115.970		2245		0.35	0.23	0.51	0.10	55	0.32	168
EWT		152.087	30	91		0.82		-0.09	0.19	25	0.32	.00
D.W.I	-4.115	152.007	30	91	0	0.02		-0.09				

TABLE II-4 (Continued) Station A₁ E₁ A₂ A₀ Long. Elev. NOBS NW RMS0 RMS1 Lat. Code 39.827 26.322 -0.70 243 0.34 EZN 387 14 0.49 0.32 -0.76 0.51 190 0.17 36.121 -94.190 630 FAV 0.28 -94.191 404 0.15 137 36.091 0.26 FAY 210 -0.84 -68.467 FRC 63.733 45 1018 16 0.64 0.50 -0.60 0.50 169 0.21 FCC 58.762 -94.087 39 1141 16 0.27 0.16 -0.49 0.15 37 0.26 65 FDF 14.733 -61.156 510 8 0.71 -0.11 0.97 71 134 0.36 FEA 39.619 -121.246 1227 0.29 -0.24 63 FEL 47.875 8.017 1485 96 6 0.29 -0.28 FFC 54.725 -101.978 338 1731 15 0.40 0.30 -0.84 0.32 12 0.18 82 FGU 40.926 -109.386 1982 424 13 0.43 0.37 0.02 0.24 249 0.24 165 FHC 0.87 0.26 283 0.28 158 682 16 0.34 40.802 -123.985 610 0.19 FIR 43.774 11.255 40 208 9 0.67 0.95 35.293 -111.702 2445 6 0.29 FLG 101 1.34 48.762 -0.482 230 16 0.39 0.22 0.01 0.46 296 0.04 17 FLN 1291 -0.88 1.01 53 38.802 -90.370 10 0.66 0.43 FLO 160 287 FOC 45.695 325 0.53 0.64 0.73 110 40.863 -73.886 63.747 -68.547 FOR 24 61 3 0.39 0.25 13 0.42 0.34 8 0.30 0.23 -0.85 0.38 82 18 384 FRB 88 FRE 36.767 -119.797 124 0.49 0.26 310 794 15 0.44 0.18 -0.16 0.51 340 0.14 11 FRI 36.992 -119.708 119 37.836 -90.486 161 6 0.83 FRM -0.25 52 FRR -18.717 47.599 1554 64 4 0.24 0.06 42.833 74.617 655 2238 17 0.33 0.31 0.73 0.14 251 0.07 160 FRU 0.48 0.14 131 0.26 16 0.37 0.31 FSJ 54.433 -124.250 772 1675 5.470 -73.738 2580 FIIO 106 0.67 -0.24 FUR 48.166 0.34 0.28 0.14 0.21 358 0.16 161 11.276 565 1514 17 37.983 -90.426 305 127 0.29 -0.79 FVM 7 13 0.51 0.18 66.566 -145.231 137 0.25 0.69 330 0.15 158 FYU 575 GAR 39.000 70.317 1300 1817 17 0.54 0.27 -0.30 0.58 335 0.28 94 13.604 77.436 0.39 -0.16 GBA 1858 36.974 -111.593 1339 0.71 0.51 0.91 0.37 172 0.52 99 GCA 522 15 **GDH** 69.250 -53.533 23 1156 17 0.45 0.24 0.14 0.11 254 0.53 101 GEN 44.418 8.930 53 52 0.22 -0.95 3 38.900 -77.067 43 159 GEO 0.30 0.08 GIL 64.975 -147.495 16 0.64 0.36 -0.58 0.67 14 0.31 162 350 2342 GIP 50.592 100 0.57 GLA 33.052 -114.827 627 221 13 0.37 0.32 0.56 0.03 82 0.28 79 55 3 0.10 GLD 39.751 -105.221 1762 0.93 0.28 439 12 0.55 0.49 356 0.39 164 GLP 40.287 30.310 560 -0.41 GLS -25.035 128.296 600 121 8 0.42 -0.60 GMA 0.08 0.15 329 0.14 68 65.429 -161.232 858 1524 16 0.32 0.30 GNZ -38.644 178.022 30 992 10 0.78 0.25 0.56 0.95 128 GOA 15.483 73.817 143 7 0.87 0.07 0.22 0.28 282 0.26 97 GOL 39.700 -105.371 2359 17 0.35 0.48 1241 57.698 0.20 GOT 11.978 9 0.41 0.62 253 253 -0.38 -0.79 GPA 40.287 30.310 560 83 0.68 GRC 47.296 3.074 191 562 13 0.15 0.15 -0.07 0.05 297 7 0.40 GRE 12.047 -61.746 15 158 0.26 GRF 49.692 11.215 525 1407 16 0.36 0.29 0.18 0.29 6 0.08 13 0.71 0.65 30 0.12 82 GRM 0.54 -0.10 -33.313 26.573 610 290

				TABLE	11-	4 (Con	tinued)					
	Stat	tion										
Code	Lat.	Long.	Elev.	NOBS	NW	RMS0	RMS1	A ₀	A ₁	<u>E</u> 1	A2	E2
GRR	48.388	-0.858	220	1297	16	0.38	0.26	0.14	0.30	279	0.22	169
GRS	39.500		1550	1833	16	0.49	0.41	0.13	0.41	42	0.28	142
GSC		-116.805	989	116	6	0.38		0.73				
GUA	13.538		230	541	15	0.87	0.64	-0.49	0.69		0.41	
GWC	55.292	-77.753	8	773	15	0.42	0.31	-0.83	0.43	51	0.12	117
HAL	44.633	-63.600	56	344	13	0.44	0.25	0.07	0.40	250	0.38	44
MAH	53.465	9.925	30	206	10	0.37	0.35	0.92	0.16	134		
HAN	46.603	-119.467	329	53	3	0.50		0.04				
HAU	48.005	6.350	570	762	16	0.33	0.23	-0.04	0.19	302	0.26	178
нвм	39.402	-120.153	1804	66	3	0.40		1.01				
HDM	41.486	-72.523	24	74	6	0.44		0.23				
HEE	50.883	5.983	100	410	12	0.35	0.28	0.35	0.29	145	0.12	118
HEI	49.399	8.726	560	53	6	0.41		-0.12				
HEN	22.000	120.750	22	76	4	0.18		2.65				
HFS	60.134	13.696	265	1404	16	0.47	0.43	-0.51	0.23	271	0.13	85
ннм	48.349	-114.027	1100	1098	16	0.37	0.22	-0.43	0.36	323	0.24	135
HKC	22.304		27	1376	18	0.64	0.47	0.78	0.60	194	0.10	112
HKT	29.950	-95.833	-122	226	12	0.26	0.18	0.28	0.16	226	0.27	67
HLE	51.500	11.950	92	157	8	0.16		-0.61				
HLG	54.185	7.884	41	114	7	0.51		0.84				
HLW	29.858	31.342	116	865	17	0.66	0.47	0.40	0.50	226	0.41	173
HNR	-9.432	159.947	72	1042	14	0.44	0.35	-0.05	0.20		0.33	
HOF	50.314	11.877	566	149	7	0.34		-0.21				
HON	21.322	-158.008	2	597	12	0.35	0.30	1.05	0.27	228		
HSS	42.965	141.232	215	213	10	0.59	0.35	0.52	0.72	204		
HUA	-12.038	-75.323	3313	475	16	0.64	0.44	0.94	0.64	212	0.14	134
HVD	-30.604			93	7	0.57		0.41				
HAO		-155.293	-	553	12		0.34	0.78	0.40	232		
HWA	23.967		18	115	6	0.65		1.66				
НҮВ	17.417	78.553	510	1954	15	0.34	0.25	-0.55	0.21	106	0.23	113
IAS	47.193			753	14	0.56	0.35	-0.27	0.51	109	0.39	
IFR	33.517			1199	17	0.63	0.26	0.32	0.80	168	0.22	95
ILG	77.947			88	6	0.35		-0.60				
ILT		-178.700	0	1835	16	0.29	0.20	-0.06			0.30	
IMA	66.068	-153.678	1380	845	15	0.33	0.14	-0.29	0.42	324	0.24	47
INH	-19.547	169.273	110	72	5	0.56		-0.51				
INK		-133.500	46	1909	17	0.34		-0.66	0.21		0.15	
IRK	52.272	104.310	467	1961	17	0.48	0.27	0.00	0.57		0.10	
ISK	41.066	29.059	132	1039	200	0.51		-0.59	0.45		0.03	ALCOHOL:
ISO	44.183	7.050	876	874	15	0.45	0.38	0.03	0.25	285	0.20	151
IST	41.046		50	1178	17		0.52	0.08	0.20	131	0.62	170
ITM	37.180	21.927	400	56	5	1.20		-0.42				
IZM	38.398	27.262	630	340	10	0.60	0.45	-0.22				
JAN	39.657	20.851	540	467	15	0.45	0.33	0.26			0.26	
JAS	37.947	-120.438	457	2065	17	0.26	0.11	0.14	0.30	31	0.16	152
JAY	-2.500	140.667	400	196	9	0.70		-0.34				
JCT	30.479	-99.802	591	421	13		0.36	-0.81	0.04	290	0.28	178
JEN	50.952	11.583	193	112	6	0.16		-0.09				
JER	31.772	35.197	770	1428	16			0.73			0.29	
JOS	48.496	20.539	280	681	14	0.45	0.31	-0.16	0.42	16	0.44	77

TABLE II-4 (Continued) Station A₀ A₁ Eı A₂ Long. Elev. NW RMS0 RMS1 Code Lat. NOBS 0.63 -20.777 116.859 15 182 -0.53 KAA 67.143 515 0.55 0.20 0.94 0.46 189 0.61 162 KAR 24.933 34 850 33.767 0.51 0.38 0.45 KAS 41.372 1364 17 0.21 75 0.43 8 KAT 39.200 56.267 90 1412 17 1.08 0.21 1.09 1.46 343 0.26 120 34.541 69.043 1920 0.47 KBL 1723 0.25 -0.14 0.51 237 0.26 132 78.917 11.924 17 0.59 0.29 0.88 0.71 251 0.07 156 KBS 46 1255 KDC 57.748 -152.492 0 1745 16 0.35 0.29 -0.17 0.02 335 0.28 16 KDZ 41.641 25.350 329 361 11 0.42 0.41 0.05 0.12 220 KEB 38.798 38.728 739 115 0.40 0.98 0.37 67 KED 12.926 -12.321 3 -1.12 34.352 47.106 1310 905 16 0.69 0.45 0.05 0.62 236 0.50 49 KES 31.995 -4.455 1124 313 14 0.55 0.39 0.84 0.52 156 0.28 93 7 0.59 -4.333 78 KET 152.036 17 0.27 2201 17 0.32 0.20 0.14 0.33 172 0.13 178 80 KEV 69.755 27.007 KEW 51.468 -0.313 5 257 9 0.33 0.10 13.579 700 2084 17 0.43 0.27 -0.32 0.46 3 0.12 22 KHC 49.131 18 0.62 0.28 0.69 0.75 253 0.24 KHE 80.617 58.050 100 1713 KHI 34.143 58.642 1600 186 7 0.23 0.18 37.483 71.533 1850 1930 18 0.53 0.34 0.61 0.52 310 0.25 109 KHO 0.54 0.23 115 0.33 84 -4.741 175 17 0.46 -0.85 6.361 719 KIC 14 0.47 0.44 -0.78 0.13 13 KIM -28.752 24.780 1321 261 0.20 100 KIP 21.423 -158.015 70 814 13 0.38 0.29 0.78 0.20 256 2523 0.44 67.840 20.417 18 0.34 -0.28 0.37 245 0.14 96 KIR 390 0.28 0.36 164 47.017 28.867 49 16 0.58 -0.63 0.58 94 KIS 1108 18 0.42 -0.29 0.22 281 KJF 64.199 27.715 160 1378 0.35 KJN 64.085 27.712 1529 18 0.28 0.17 -0.36 0.29 210 -30.784 121.458 17 0.34 0.30 -0.82 0.25 191 0.02 38 KLG 350 2034 0.47 -0.50 0.79 225 KLS 56.165 15.592 11 259 9 0.22 KMU 42.237 142.967 180 706 14 0.60 0.37 0.38 0.69 156 0.32 110 0.34 70 KNA -15.750 128.767 901 13 0.50 0.41 -0.72 0.27 40 KOA -6.224 155.619 65 270 8 0.36 -0.95 KOD 10.233 77.467 2343 1952 16 0.39 0.23 0.88 0.37 188 0.21 113 KON 59.649 9.598 200 1553 17 0.30 0.17 0.09 0.33 283 0.09 133 -20.562 164.281 0.16 0.51 10 0.37 55 13 0.65 0.45 1008 KOU 17 KPH 21.576 -158.275 0 91 0.44 0.42 0.35 KPK 39.583 -121.305 899 54 0.66 19.940 KRA 50.058 223 1931 17 0.13 -0.04 0.21 337 0.11 74 0.26 0.09 0.44 157 0.21 69.724 30.062 10 KRK 0 645 13 0.40 KRL 49.011 8.412 114 618 15 0.52 0.45 0.79 0.41 11 0.04 41 -37.925 175.537 2166 15 0.74 0.43 -0.01 0.51 323 KRR -16.852 29.618 1380 17 0.68 -0.60 0.41 326 0.38 83 1365 0.57 KRT -4.353 152.052 20 64 5 0.72 0.47 46.333 340 35.892 923 17 0.34 16 0.56 40.650 KRV 1634 0.27 -0.42 0.20 22 0.23 142 33.824 0.60 183 0.71 KSA 1320 0.37 0.12 108 -25.850 KSR 26.897 1623 11 0.96 0.85 0.20 0.73 167 123 KTG 70.417 -21.983 17 0.54 0.55 0.64 122 0.13 165 1510 0.30 KUG -10.183 123.667 52 126 1.36 0.63 KUL. 37.900 69.750 605 11 0.58 0.41 -0.11 0.59 312 559 25.123 0.41 KUN 102.740 1922 0.73 104 5 11 0.27 0.15 0.70 202 KUR 45.233 147.867 564 0.53

				TABLE	11-4	(Cont	tinued)					
	Sta	tion										
Code	Lat.	Long.	Elev.	NOBS	NW	RMS0	RMS1	A ₀	A ₁	<u>E</u> 1	A2	E ₂
KYS	35.198	140.148	180	598	14	1.02	0.31	0.95	1.54	74	0.19	132
KZN	40.307	21.771	900	253	10	0.47	0.37	0.03	0.41	-		
LAH	31.550	74.333		917	17	0.44	0.35	-0.21	0.31	316	0.25	81
LAN	36.050	103.833		116	7	0.68	0 20	0.40	0 51	210	0 110	
LAO	46.669	-106.222	744	1148	17	0.55	0.30	-0.11	0.51	310	0.40	51
LAR	41.314	-105.583	2400	329	12	0.55	0.55	0.12	0.12	9		
LAT	-6.712	146.990	37	603	11	0.30	0.20	0.09	0.35	190		
LAW		-95.250	0	262	10	0.42	0.36	-0.95	0.38	39		
LBF	46.987			885	16	0.35	0.17	-0.00	0.30		0.37	4
LCG	21.145	-101.725	2200	161	9	0.45	0.28	1.68	0.49	74		
LEE	37.243	-113.377	1067	112	8	0.42	0.29	1.08	0.49	37		
LEM		107.617		1469	16	0.83	0.46	0.79			0.51	31
LF4		-106.944	707	169	5	0.49	10000000	-0.19				
LFF	44.937	0.736	160	566	15	0.32	0.28	0.33	0.07	331	0.22	14
LHA	29.637			127	6	0.21		1.23				
LHC	48.417	-89.267	196	580	15	0.40	0.29	-0.57	0.37	60	0.16	68
LHN	61.049		505	540	13	0.47	0.26	-0.09	0.49		0.18	66
LIC	6.224	-5.028	100	374	14	0.50	0.41	-0.72	0.34		0.22	82
LIS	38.716	-9.149	77	309	15	0.55	0.46	0.93	0.38			
LJU	46.043	14.533		1524	16	0.62	0.40	0.07	0.67		-	
LMG	-8.908	148.150		216	8	0.61		0.03				
LMP	-16.426	167.800	60	330	7	0.47		-0.06				
LMR	43.333	6.509		434	13	0.40	0.33	0.07	0.23	284	0.20	11
LMT	-41.610	146.152	349	90	3	0.18		0.72				
LND	43.040	-81.183	246	138	5	0.43		-0.57				
LNR	-15.852	168.160	8	410	8	0.36		-0.25				
LNS	45.289	6.915	1480	1053	15	0.62	0.25	0.51	0.63	267	0.45	4
LOM	6.122	1.213		56	4	0.58		0.50				
LON		-121.810		1290	16	0.47	0.26	0.03	0.40			
LOR	47.267	3.851	520	1629	17	0.36	0.20	-0.12	0.22	268	0.36	6
LOT	45.448	23.769	1240	61	4	0.36		-0.99				
LPA	-34.909		14	221	14	0.69	0.49	-0.12	0.55	69	0.43	
LPB	-16.533		3292	499	17	0.58	0.38	0.06	0.33		0.52	61
LPF	48.032	-1.042		458	15	0.42	0.29	0.03	0.37		0.30	22
LPO	44.683	1.187	330	533	15	0.29	0.18	0.35	0.17	120	0.25	15
LPS	14,292	-89.162	1000	620	13	0.64	0.46	0.36	0.29	238	0.53	54
LRG	43.454		100	479	13	0.33	0.28	0.28	0.15		0.20	9
LSF	46.250	1.534		661	15	0.29	0.14	0.14	0.24		0.31	í
LSM		-116.278		290	12	0.42		0.54	0.40			
LUB		-101.867				0.38					0.20	
LUC	-15.518	167 120	150	947	•	0 44	0.29	0 10	0.94	222		
LUG	49.600	167.130		867	12		0.28	-0.18			0.16	00
LVV	49.817	6.133		395 890	15	0.31	0.26	0.12				
LWI	-2.238	28.800		903	17	0.42	0.43	0.12	0.30		0.36	
MAG	59.550			1366	16	1.05	0.34	0.20	1.32		0.26	
MAK	43.017	47.433	10	558	14	0.74	0.49	1.03	0.59		0.57	
MAL	36.727 14.662	-4.411 121.077	60 70	230 630	15		0.24	0.35	0.71		0.37	
MAT	36.542	138.209		2641	15		0.29	-0.54	0.38			
	30.372	62.875		1767	17		0.39	-0.11			0.06	

				TABLE	11-4	(Cont	inued)						
	Sta	tion											
Code	Lat.	Long.	Elev.	NOBS	NW	RMS0	RMS1	<u>A</u> 0	<u>A</u> 1	<u>E</u> 1	A2	E ₂	
MBC MBO	76.242	-119.358 -16.955	15	2849 308	17 13	0.34	0.26	-0.41 0.59	0.14	70	0.26	49	
MBT	-21.170	119.742	200	489	10	0.38	0.30	-0.72	0.38	358	0.07	24	
MCC		-118.585 158.956	578 14	367 327	14	0.53	0.27	0.32	0.52	310	0.27	21	
MDC		-121.914	1173	104	6	0.45		1.11					
MDR MDZ	13.000 -32.883	80.183 -68.850	15 826	541 183	12	0.50	0.37	0.40	0.38		0.50	157 77	
MED	3.550	98.683	32	356	10	0.52	0.30	-0.33	0.86		0.30	"	
MEK	-26.613			1620	16	0.39	0.38	-0.84	0.08		0.08	96	
MES	38.199	15.555	45	245	10	1.11	0.71	0.28	1.29				
MFF	46.601	-0.143		545	15	0.31	0.17	0.26	0.21		0.29	179	
MFP	3.342	8.661		142	12	0.51	0.45	0.66	0.34	178			
MGL MGN	40.925	-121.557 32.181	975 750	57 273	7	0.35		-0.09 0.73					
мнс	37.342	-121.642	1282	1571	16	0.38	0.29	0.69	0.33	86	0.07	12	
MHI	36.300	59.495	1100	57	3	0.20		0.57					
MHK	39.187		314	78	6	0.62		-0.18					
MHT		-96.581	200	206	6	0.69		-0.66					
MID	59.428	-146.339	37	62	6	0.62		1.00					
MIM	45.244	-69.040	140	139	7	0.34		0.17					
MIN		-121.605		1374	16		0.21		0.37		0.05	8	
MIR	-66.550	93.000	30	1403	16	0.54	0.33	-0.31	0.65		0.21	79	
MIZ MJZ	39.134	141.136	63	219	10	0.70	0.09	1.40	0.21				
	-43.987	170.466		1300	11	0.30	0.29	0.04	0.10	30			
MKS	-5.067	119.633	28	212	9	1.01		1.05					
MLR	45.492 42.958	25.944	450	344 88	10	0.56	0.51	0.74	0.43	253			
MMA		1.083	426	306	12	0.46	0 40	0.76	0 28	242	0.13	00	
MNG	-40.619	175.482	396	1680	14	0.79	0.36				0.50		
MNL	33.147	73.750	436	425	8	0.38		0.68					
MNT	45.502		112	975	18		0.34	-0.13	0.76	104	0.27	8	
MNV	38.433	-118.153	1507	554	15	0.30	0.20	0.30	0.07	4	0.31	145	
MNW	-45.780	167.619	155	877	9	0.32	0.30	0.00	0.17	227			
MNY	44.961	5.691	422	786	15	0.57	0.29	0.19	0.61	234	0.43	8	
MOA	47.850	14.266	572	105	6	0.39		-0.04					
MOK		-157.737	0	86	7	0.55		0.37					
MOM	-2.074	147.411	10	254	10	0.45	0.37	0.38	0.44				
MOO	-42.442	147.190	325	565	10		0.27	0.66	0.34		0 20	161	
MOS	55.738	37.625	124		17	0.37		0.03	0.13	190	0.29	101	
MOX	50.646	11.616	454	2089	17	0.23	0.21	-0.13					
MOY	51.683		0	1485	17	0.40			0.47		0.05		
MRG	39.633	-79.954 59.588	282 999	493 1345	14	0.66	0.32	0.89	0.81		0.14		
MSO		-113.941		371	15	0.34	0.27	0.90	0.37		0.03	T-10-100-100-100-100-100-100-100-100-100	
MSZ	-44.671	167.917	38	1166	12		0.34				0.62	43	
MTD	-16.780	31.583	967	494	11	0.53	0.42	-0.61	0.45	285	0.23	112	
MTE	40.403	-7.537	815	62	6	0.39		0.57					
MTN	-12.846 -31.978	131.130 116.208	155 253	673 2175	13	0.63	0.45	-0.48 -0.52			0.35	72	

TABLE II-4 (Continued) Station <u>E</u>1 A₀ A2 A₁ Code Elev. NOBS NW RMS0 RMS1 Lat. Long. 0.72 0.53 MWI 16.713 -62.222 6 36.804 1692 860 0.35 0.72 268 0.27 147 NAI -1.274 15 0.68 1.56 NAN 32.063 118.783 86 6 0.51 0.01 60.824 918 NAO 10.832 379 16 0.54 0.22 -0.75 0.66 258 0.09 NDF -17.757 177.450 30 228 0.57 1.47 18 0.50 0.36 -0.42 NDI 28.683 2649 77.217 230 0.46 294 0.14 NEL 35.712 -114.844 0 90 4 0.32 0.54 NEM 43.328 145.587 26 149 8 0.74 0.34 -0.77 1.09 200 NEW 48.263 -117.120 760 2134 16 0.43 0.20 -0.47 0.51 330 0.16 158 0.37 169 NGS 32.732 129.870 226 0.56 0.37 0.84 0.50 27 11 NHA 12.210 109.212 159 5 0.44 0.17 -29.042 NIA 167.960 130 103 0.50 0.95 NIE 49.424 0.23 0.28 0.12 343 0.23 74 20.322 17 0.29 555 1633 0.42 219 NIK 52.974 -168.853 207 286 0.38 0.26 -1.04 NIL 33.650 1288 0.45 0.24 -0.19 0.48 73.252 0.54 NKM 35.448 -5.410 0.35 0.46 0.53 255 158 171 10 NLG 17.067 79.267 220 197 8 0.46 -0.34 NLM 39.032 -76.981 114 50 4 0.65 -0.12 0.46 NNA -11.988 -76.842 575 234 12 0.57 -0.57 0.19 227 0.42 43 81.600 -16.683 -0.24 NOR 36 1345 17 0.48 0.33 0.23 165 0.49 151 NOU -22.310 166.451 105 966 14 0.60 0.40 0.36 0.23 123 0.53 16 NP-76.252 -119.372 59 557 14 0.36 0.22 -0.06 0.32 67 0.23 71 NPL 40.847 14.258 7 60 7 0.93 1.06 NPS 35.262 370 113 8 -0.60 25.612 0.86 NRN 41.433 76.000 2849 366 11 0.31 0.20 0.15 0.39 NRR 39.572 -119.849 1650 233 0.32 0.16 0.29 30 12 0.37 0.71 346 0.16 150 48.630 -116.963 NTI 823 1560 16 0.52 0.15 -0.27 NUE -19.076 -169.928 56 50 0.15 0.56 NUR 60.509 24.651 102 2466 18 0.21 0.11 -0.39 0.05 223 0.24 113 0.33 0.06 0.54 14 NVL -70.767 11.833 87 738 16 0.52 0.29 99 0.37 58 -0.47 OBN 55.167 36.600 0 1526 16 0.43 0.22 0.40 144 OHR 41.111 20.799 739 360 14 0.70 0.28 -0.09 0.95 242 0.24 62 653 0.14 0.12 0.12 1 0.35 OIC 34.099 135.317 776 13 0.30 75 OIS 34.105 135.327 678 654 0.36 0.10 0.04 196 0.25 13 0.31 21.691 -158.012 0.55 OPA 150 125 0.87 0.15 ORT 35.942 -84.320 472 0.45 0.39 66 0.32 87 0 12 0.59 744 14 0.23 0.49 179 ORV 39.555 -121.500 360 0.38 -0.22 0.33 172 45.394 -75.716 OTT 83 1029 18 0.55 0.33 -0.21 0.61 100 0.15 OUA -20.775 167.244 29 293 6 0.48 0.14 25.896 0.40 0.34 0.20 199 0.24 OUL 65.085 1106 18 -0.67 OXM -99.688 2700 7 19.297 112 0.81 0.72 0.34 0.62 87 MYO 35.420 139.243 600 307 0.61 0.03 0.75 67 13 0.33 -6.301 298 43 PAA 155.491 699 9 0.23 -0.94 0.43 45.409 11.886 12 PAD 130 2.00 -17.662 -149.580 549 0.51 0.38 0.24 12 0.64 114 PAE 60 14 0.64 41.004 -73.909 PAL 300 10 0.60 0.48 -0.13 0.58 PAO 40.598 110.018 0 105 6 0.71 0.36 34.148 -118.172 0.34 0.25 0.28 59 0.13 32 PAS 295 1646 16 0.39 45.183 144 PAV 9.174 77 1.29 0.39 0.53 0.42 299 PBA 11.667 92.717 271 11 0.61 0.73

				TABLE	11-4	(Con	tinued)						
	Stat	tion											
Code	Lat.	Long.	Elev.		NW	RMS0	RMS1	A ₀	<u>A</u> 1	E	A2	<u>E</u> 2	
PBJ PDA PEK	16.437 37.743 40.040	-95.407 -25.662 116.175	213 35 0	124 115 514	7 8 15	0.65 0.26 0.53	0.35	-0.12 1.26 -0.10	0.54		0.08	68	
PEL PET	-33.144 53.017	-70.685 158.650	690 25	242 1259	12	0.58	0.57	-0.54 -0.25	0.18		0.61	25	
PHC PIM		-127.432 -101.882	33 81	652 73	13	0.18	0.09	0.66	0.13	333	0.21	. 75	
PJD PJG PKR	65.035	-147.508 144.867	740 138	500 93 61	13 8 4	0.70 1.00 0.57	0.40	-0.39 -0.54 0.74	1.00	357	0.12	81	
PLG PLV	20.806	23.446	580 90	601 350	15 9 4	0.57	0.34	-0.04 1.68	0.82		0.43	175	
PMA PMG PMO	-9.409	-160.497 147.154 -147.897	314 70 2	51 1558 679	14	0.24 0.44 0.61	0.24	0.30 0.02 0.34	0.50 0.30		0.20	170	
PMR PNL		-149.131 -139.397		2520 76	15	0.38	0.21	-0.57 0.35	0.36	50	0.19	20	
PNS PNT	-16.267	-68.473 -119.617		446 1973	17 16	0.58	0.48	0.24	0.28	COLUMN TO THE REAL PROPERTY.	0.38		
P00	18.533	73.850	556	1932	15	0.41	0.33	-0.27	0.35		0.12		
PPN PPT		-149.432 -149.576	100 260	715 848	16 16	0.68	0.56	0.44	0.27		0.50	and the state of	
PRA		14.433		1221	17	0.31	0.23	0.27	0.24		0.18		
PRE	-25.753	28.190	1333	1121	17	0.47	0.27	-0.11	0.46	31	0.29	136	
PRI		-120.665		1581	17	0.44	0.29	0.94	0.18		0.42		
PRK PRS	39.246 36.332	26.272 -121.370	100 363	724 155	14	0.40	0.32	0.16	0.23	243	0.23	137	
PRT	43.883	11.092	62	84	6	0.31		0.84					
PRU PRY	49.988 -26.928	14.542 27.473	302	115	17	0.40	0.22	-0.08 -0.44	0.44	and the same of the same of	0.23	120	
PRZ PSO	42.483	78.400 -77.325		1108	18	0.41	0.26	1.05	0.25	165	0.36	109	
PSZ	47.919	19.894	940	491	13	0.37	0.29	-0.13	0.35	9	0.15	119	
PTL PTN	38.049 44.572	23.865 -74.983	500 238	247 50	9	0.63		-0.43 -0.47					
PTO PUL	41.139 59.767	-8.602 30.317	88 65	752 1341	16	0.30	0.25	-0.37	0.17		0.18		
PVC	-17.740	168.312	80	557	7	0.45		-0.04					
PVL PYA	43.147	25.172 43.058	187 497	495 744	12	0.27	0.18	0.45			0.28		
PYR QCP	34.568	-118.741 121.077	1247 58	85 572	7	0.31	0.63	0.77	0.27	530			
QMB	53.765	-1.858		53	4	0.17	0.03	0.30	0.21	239			
QUE	30.188	66.950	1721	2594	18	0.43	0.18	0.25			0.31		
QUI	-0.200	-78.500		261	13	0.65		1.48			0.22		
RAB RAC	-4.191 50.083	152:170 18:194	184 209	1406 145	15	0.57	0.39	-0.63 0.59	0.39	300	0.42	134	
RAL RAM	-4.220 37.766	152.202 41.292	91	107 115	8	0.65		-0.28 0.41					
RAO		-177.918		73	3	0.44		0.15					

TABLE II-4 (Continued) Station E A₀ A₁ A₂ Long. Elev. NOBS NW RMS0 RMS1 Lat. 14 RAR -21.212 -159.773 28 436 12 0.82 0.56 0.14 1.07 0.56 95 -6.841 321 17 0.70 0.32 70 0.39 156 34.009 0.61 RBA 39 0.13 -6.840 33.929 RBZ. 116 279 12 0.51 0.46 0.07 0.32 290 -0.20 RCD 44.075 -103.208 995 144 0.66 38.106 0.98 0.39 74.687 -94.900 1775 18 0.46 0.29 RES 15 -0.46 0.46 34 0.21 100 REY 64.139 -21.906 44 208 11 0.60 0.40 1.61 0.53 60 0.30 99 RHO 36.437 28.224 45 107 0.45 1.00 -33.829 151.158 25 1523 17 0.76 0.54 0.38 0.71 4 0.21 97 -23.118 -134.972 100 139 6 0.36 0.04 RMP 41.811 12.702 380 768 16 0.44 0.39 0.08 0.28 196 0.14 146 ROC 43.125 -77.592 155 178 0.45 -0.24 9 37.918 11 0.51 0.42 -91.869 200 332 -0.81 0.47 75 0.82 0.70 214 0.36 41.903 45 365 11 0.60 0.27 ROM 12,513 -45.476 169.320 ROX 106 157 7 0.54 0.26 RSL. 45.688 6.626 1583 874 15 0.52 0.36 -0.05 0.43 304 0.27 32 -15.189 -147.384 RUV 415 0.79 0.47 0.68 344 1.02 110 -0.10 13 SAM 39.673 66.990 704 875 16 0.47 0.28 0.51 0.21 260 0.47 178 -33.453 -70.662 533 166 10 0.42 0.36 SAN -0.23 0.31 138 SAO 36.765 -121.445 350 425 14 0.37 0.36 0.48 0.12 38 43.058 SAP 141.332 18 223 10 0.65 0.58 0.21 0.39 168 SAV -41.721 147.189 180 1484 15 0.45 0.32 0.75 0.39 11 0.19 117 SBA -77.850 166.756 38 1776 16 0.76 0.68 0.69 0.41 33 0.31 46 SCB 43.717 -79.233 153 128 5 0.54 0.08 16.029 -61.681 646 10 0.85 0.51 1.07 83 0.06 129 SCG 123 0.38 54.817 -66.783 SCH 540 1235 17 0.28 0.17 -0.56 0.17 108 0.27 155 61.833 -147.328 1020 SCM 536 12 0.35 0.23 0.07 0.42 324 40.795 -77.865 352 -14.926 13.572 1781 SCP 170 0.28 -0.34 SDB 751 18 0.69 0.42 0.01 0.66 53 0.41 91 47.655 -122.308 SEA 30 150 7 0.54 1.53 SEH 23.167 77.083 0 86 L 0.35 0.64 SEM 50.408 80.250 209 1651 18 0.47 0.16 -0.31 0.60 241 0.19 92 SEO 37.567 126.967 86 237 11 0.56 0.45 -0.02 0.47 123 SES 50.396 -111.042 770 1832 0.18 0.17 -0.48 0.08 45 0.05 17 59 5.400 1000 SET 36.200 0.66 0.39 -0.31 0.88 303 213 11 0.60 SFA 47.123 -70.827 232 784 16 0.63 0.43 -0.32 0.49 126 0.48 13 -41.337 146.307 213 258 0.46 0.87 37.787 -122.389 8 58 4 0.29 SFR 0.57 SES 36.462 -6.205 24 63 6 1.05 1.53 0.22 47.709 -0.923 0.38 54.942 1500 36.433 SHD 114 7 0.44 0.53 SHE 40.633 48.633 0 274 8 0.52 1.59 0.34 -0.44 SHF 46.552 -72.763 60 53 3 0.72 SHI 29.644 52.526 1595 2274 18 0.37 0.19 285 0.03 34.530 132.678 285 1589 14 0.45 0.37 -0.21 0.35 123 0.34 SHK SHL 25.567 91.883 1600 2393 18 0.50 0.35 -0.54 0.48 156 0.18 16 34.248 108.920 SIA 120 6 0.37 0.01 0.34 197 0.29 19 SIC 50.175 283 407 0.54 0.45 -66.742 -0.05 13 0.42 63.786 26 -18.058 182 SID 10 0.26 1.43 0.55 0.23 216 0.43 161 SIM 44.950 34.117 277 1326 17 0.50 0.36 0.26

					TABLE	11-4	(Con	tinuea)	13					
		Stat	tion			,			,		4 4	- 1	eig.	
	Code	Lat.	Long.	Elev.	NOBS	NW	RMS0	RMS1	A ₀	<u>A</u> 1	<u>E</u> 1	A2	E ₂	
	SIT		-135.324		788	14	0.42	0.20	0.70	0.31		0.40	155	
The first	SJG	18.112			521	14	0.75	0.52	-0.93	0.68		0.35	35	
	SKA	63.580	12.280	580	373	11	0.19	0.11	-0.34	0.24	261			
A COLOR	SKI	17.333	-62.739	306	140	8	0.52		0.02					
1 30	SKO	41.972	21.440	346	998	18	0.44	0.37	-0.24	0.14	300	0.30	8	
	040		456 400				0							
	SKR	50.667			506	12	0.58	0.39	-0.33	0.61				
	SLC		-111.848		698	16	0.36		0.03		265			
	SLD		-121.221		725	14		0.25	0.96	0.07	38	0.40	17	
	SLL	60.477			123	7	0.67		-0.54					
	SLM	38.636	-90.236	161	196	6	0.30		-0.71					
	****		454 400											
	SMY	52.731	and the second		315	11	0.69		-0.41	1.04	-			
	SNA	-70.315			269	11	0.50	0.36	-0.13			0.02	4	
	SNG	7.173			392	9	0.66	0.25	-0.31	1.36				
	SOC	43.583	39.717	192	672	13	0.44	0.37	-0.00	0.19	241	0.28	155	
	SOD	67.371	26.629	181	2730	18	0.25	0.16	-0.39	0.22	151	0.15	169	
	SOF	42.685	23.334	546	597	15	0.50	0.47	0.13	0.14	92	0.21	77	
	SOP	47.683	16.558	260	578	16	0.42	0.15	-0.74	0.49	357	0.23	20	
	SOR	22.792	-83.008	206	56	3	0.62		0.07					
	SPA	-90.000			1612	16	0.58	0.46	0.02	0.44	292	0.31	139	
	SPF	43.564			539	13	0.33	0.30	0.19	0.19		•••		
		.5.5.									-3-			
4	SPK	-43.038	146.275	425	68	4	0.74		1.27					
	SPO		-117.344	-	232	9		0.21	0.55	0.50	255			
	SRI	36.758			461	10	0.11	0.21	0.77	0.50	300			
		47.813			-		0.43	0.39	0.82	0 16	206	0 19	26	
	SRO				625	16				0.16		0.18		
	SRY	35.608	139.274	254	1140	14	0.56	0.27	-0.22	0.69	42	0.37	97	
	SSB	45.279	4.542	700	95	7	0.46		0.18					
		48.584						0 22		0 20	2110	0 10	172	
	SSC				1300	16	0.33		0.11			0.18		
	SSF	47.061	3.507		1548	17	0.38	0.21	-0.04	0.19	231	0.41	6	
	SSR	44.531		0	81	6	0.85		-1.90					
	SSS	13.681	-89.198	665	70	4	0.40		0.79					
	000	26 622	404 000	050	460				4 20					
	STC		-121.233		168	8	0.60		1.37					
	STG	-42.848	A STATE OF THE PARTY OF THE PAR		85	6	0.57		0.38					
	STJ	47.572			535	15	0.44	0.38	-0.09		49			
	STK	-31.882			509	11	0.40	0.24	-0.09	0.38		0.19	1,575	
	STR	48.585	7.766	135	1184	17	0.49	0.33	0.38	0.41	4	0.30	145	
18116	STU	48.772			956	16			-0.41			0.31	158	
	SUD	46.467	-80.967	267	319	12		0.45	-0.27	0.63	64			
	SUR	-32.380	20.728	0	96	8	0.63		0.78					
	SUV	-18.149	178.457	6	57	5	0.46		0.14					
	SVE	56.810	60.637	275	2359	18	0.30	0.29	-0.18	0.12	175	0.05	176	
	SVT	13.168	-61.245	38	114	6	0.57		0.06					
	SVW	61.108	-155.622	762	938	15	0.85	0.20	-0.01	1.16	299	0.09	26	
	SYO	-69.006	39.503		591	14	0.86	0.52	-0.26		338	0.35		
	TAB	38.067			1622	17	0.53	0.33	0.54	0.53		0.30		
	TAC	19.405			283	11	0.69	0.36	1.03		153	0.44		
							,			,				
	TAF	34.814	-2.414	820	310	14	0.53	0.31	0.48	0.58	163	0.20	76	
	TAM	22.792		and the later of t	657	17	0.49	0.46	-0.19	0.03		0.27		
	TAN	-18.917	47.552		696	10		0.40	0.44					
	TAS	41.325			2187	18	0.30	0.27	0.27		205	0.11	03	
	TAU	-42.910			1734	17	The second	0.34	0.36		11-14-15-15	0.29		
	****	-45.710	141.320	132	1134		0.55	0.34	0.30	0.54		0.29	, , ,	

TABLE II-4 (Continued) Station A1 E1 A2 E2 A₀ Code Lat. Long. Elev. NOBS NW RMS0 RMS1 152.220 8 0.43 -0.30 TAV -4.231 TCF 46.288 2.214 640 802 15 0.36 0.16 0.27 0.41 159 0.34 51.386 1360 TEH 35.738 1095 17 0.46 0.21 0.47 0.47 11 0.36 171 8 1.54 28.454 -16.240 0.63 TEN 119 33.577 0.44 TET -16.146 153 678 14 0.52 0.29 0.31 228 0.17 108 TFO 34.268 -111.270 1492 1039 15 0.44 0.35 0.53 0.36 6 0.26 108 6 0.24 -0.16 TGI 59.193 1800 32.963 94 33.875 -111.874 1134 6 0.47 0.71 THO 102 THT -17.569 -149.574 337 126 6 0.38 0.88 44.800 399 0.30 0.25 0.63 0.13 27 0.23 135 TIF 41.717 1251 17 2826 TIK 71.633 128.867 25 18 0.46 -0.95 0.33 310 0.42 123 0.26 88 8 TIM 45.737 21.222 116 0.46 1.24 TIO 30.927 -7.262 1335 387 13 0.54 0.31 0.67 0.58 182 0.19 65 41.347 19.867 197 582 16 0.53 0.35 0.43 0.52 226 0.21 140 TIR TJC 37.217 -104.691 2103 218 6 0.46 TLL -30.167 -70.804 2200 108 10 0.47 0.47 -0.30 0.04 130 150.045 205 8 0.49 0.60 TLS -5.310 41.811 -72.799 TMT 94 7 0.38 0.49 290 -6.183 106.500 14 8 0.66 -0.55 TNG 233 TNN 65.257 -151.912 504 335 11 0.61 0.38 0.32 0.74 322 TNP 38.082 -117.218 1932 0.38 0.14 0.20 0.10 107 0.46 142 329 13 8.449 815 0.42 0.42 TNS 50.224 197 10 0.21 0.03 25 TOA 62.105 -146.172 909 665 12 0.27 0.15 0.34 0.27 353 0.12 TOL 39.881 -4.049 480 1121 18 0.23 0.55 0.17 217 0.18 0.10 132 TOO -37.571 145.491 604 2683 18 0.46 0.34 0.19 0.28 314 0.34 38.075 -117.222 1890 TPH 166 8 0.34 0.47 TPM 18.983 -99.062 1500 98 5 0.38 0.42 TPT -14.984 -147.619 880 17 0.71 0.46 0.21 0.67 355 0.54 103 3 76.950 221 8.483 0 TRD 8 0.56 0.55 45.709 0.32 -0.45 0.31 204 0.35 156 TRI 13.764 126 903 16 0.44 TRN 10.649 -61.403 24 521 0.99 0.26 0.04 1.06 106 0.80 46 13 0.06 0.39 257 0.08 116 0.59 0.65 17 0.40 114 -0.36 0.97 87 0.38 129 0.34 TRO 18.928 15 1917 0.18 69.632 17 TRR -42.304 146.450 579 1166 14 0.56 0.30 TSK 36.211 140.110 280 1532 14 0.73 0.32 62.930 -156.022 14 0.73 0.23 -0.38 0.85 293 0.46 176 TTA 914 559 TTN 22.750 121.150 9 158 7 0.40 1.91 TUC 32.310 -110.782 985 1704 17 0.35 0.31 0.04 0.20 335 0.11 113 TUL 35.911 -95.792 0.40 0.30 -0.52 0.44 250 0.20 74 256 1202 14 47.015 -122.908 54.433 119.900 TUM 356 0.67 0.24 0.30 0.65 310 0.56 172 20 12 0.38 TUP 0 1075 15 0.25 -0.02 0.42 236 0.16 98 TVO -17.782 -149.252 660 562 14 0.62 0.61 0.61 0.11 246 UAV 8.604 -71.145 1550 240 0.79 0.66 -0.33 0.58 342 11 1489 0.04 0.26 284 0.27 127 0.81 0.27 54 0.34 115 40.322 -109.569 1596 UBO 17 0.40 0.30 UCC 50.798 4.359 105 702 15 0.43 0.31 0.27 54 0.34 115 UCT 41.832 -72.251 79 240 255 UDD 60.090 0.39 0.36 -0.80 0.21 233 13.607 10 UKI 39.137 -123.211 199 222 9 0.37 0.27 1.14 0.33 70 UME 63.815 20.237 16 2361 18 0.39 0.19 -0.58 0.37 234 0.32 94 -99.178 2257 8 0.73 0.88 UNM 19.329 158 UPP 59.858 2296 17 0.32 0.25 -0.61 0.27 255 0.05 107

17.627

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					TABLE	11-4	4 (Con	tinued)						
4		Stat	tion											
	Code	Lat.	Long.	Elev.	NOBS	NW	RMS0	RMS1	A ₀	<u>A</u> 1	<u>E</u> 1	A2	E2	
	URS	33.538 48.633		25	72	5	0.36	0.05	0.48				06	
	VAH		22.300 -147.636	159	1867 694	17	0.30	0.25	0.26	0.17		0.18		
	VAL	51.939 35.407	-10.244 24.200	14 225	751 658	15 15	0.65	0.63	0.58	0.19		0.13		
	VAN VAR	37.950 25.300	58.100 83.017	250 88	1072 297	17	0.42	0.32	-0.33 -0.53	0.36		0.22	122	
	YAY	41.321	22.570	168	431	15	0.56	0.46	-0.07	0.50	-	0.37	14	
	VHM VIC	17.177 48.519	-96.745 -123.415	197	237 1049	11	0.48	0.43	-0.09	0.28		0.04		
	VIE	48.248	16.362	198	995	17	0.55	0.38	-0.16	0.49	76	0.21	36	
	VIS	17.717	83.300	41	186	7	0.61		0.54			0.21	50	
	VKA	48.265	16.318		1144	17	0.45	0.36	-0.14			100 miles	37	
	VLA VLS	43.120 38.177	131.893 20.590	75 375	1724 683	13 13	0.58	0.33	-0.04 -0.21	0.65		0.08	152	
	VLV	-39.790	-73.276	12	58	6	0.78		0.08					
	VOU	46.399	5.651	495	590	14	0.28	0.18	0.04	0.22				
	VRI VUL	45.870 -4.283	26.725 152.146	400 332	1144	16	0.59	0.47	0.19	0.51	34	0.35	122	
	VUN	-18.043	178.464	160	209	6	0.41		0.03					
	VYB	60.717	28.800	0	92	7	0.68		-0.90					
	WAB	-5.495	143.728		646	12		0.25	1.01	0.65	213	0.34	104	
	WAN	-4.194 52.242	152.176 21.024	25 110	94 66	8	0.65		-0.21 0.46					
		-19.935	134.357	366	78	8	0.56		-1.14					
	WDC		-122.540	300	522	14	0.91	0.41	-0.48	1.05	293	0.25	155	
		-41.286	174.768	122	853	14	0.72	0.59	-0.31			0.22		
	WES	42.385 -66.259	-71.322 110.527	60 10	482 236	17	0.41	0.27	0.35	0.42		0.22	72	
		-22.567	17.100		820	18	0.82	0.53		0.61		0.65	80	
	WIT	52.813	6.668	17	1101	15	0.39	0.25	1.16	0.23	310	0.32	151	
	WKU	34.188	135.173	10 775	167 1179	10	0.58	0.56	0.09	0.20				
	WMO	34.718	-98.589	505	544	15 14	0.36	0.29	0.17	0.13		0.27	17	
		-19.948	134.351	245	1662	17	0.37	0.32	-1.06	0.23		0.11	74	
	WRM	49.833	5.381	242	279	10	0.31	0.30	1.70		95			
	WRS	34.150 39.050	71.408	343 120	1695 344	17	0.63	0.40	-0.34	0.65	W. W. Com.	0.40	74	
		-37.985	176.988	43	116	5	1.17	0.39	-0.31	0.32	143			
	WUC	30.543	114.350	26	56	5			0.32					
	YAK		129.717			16		0.23		0.25	186	0.26	25	
	YER		28.283		156 2122	7	0.22	0.24	-0.02 -0.76	o lik	200	0 11	E h	
	YKT		-138.877		62	5	0.36	0.24	0.05	0.44	309	0.11	24	
	YOU		148.382	503	268	8	0.53		0.33					
	YSS	47.017	142.717	75		15		0.21		0.20		0.14		
	ZAG	45.817 50.383	15.983 103.283	155	576 1847	15 18	0.51	0.35		0.30		0.47	11 11 11 11 11 11	
	ZSC	31.097	121.187	100	96	5	0.50		-0.01					
	ZUL	47.481	8.390 8.580	740 604	250	10	0.48	0.43	-0.83	0.40	331			
	LUK	47.309	0.500	004	117	7	0.42		-0.77					

observed at Suffield; both are excellent stations, with RMS1 values of 0.13 and 0.17 sec, respectively. It is difficult to escape the conclusion that the source of the anomaly observed at Edmonton must be relatively shallow under that station.

In summary, the azimuthal terms are important (with the A_1 term generally much more significant) and, in general, their application should lead to reduction in the rms error commensurate with that resulting from usage of the A_0 term alone. The azimuthal terms show substantial correlations over very large areas, but occasionally a dramatic, well-established change may take place over a short distance.

	(a)	Cross-Correl	ation Coeffic	ients	
	TR	S&J	H&T	L&D	C&H
TR	_	0.675	0.764	0.800	0.683
S&J	0.675	-	0.649	0.744	0.612
H&T	0.764	0.649	-	0.727	0.661
L&D	0.800	0.744	0.727		0.623
C&H	0.683	0.612	0.661	0.623	-
		(b) Regression	on Coefficien	ts	
		Dep	oendent Varia	ble	
	TR	L&2	H&T	L&D	C&H
TR	_	0.882	0.825	1.070	0.931
S&J	0.517	-	0.508	0.766	0.611
H&T	0.708	0.830		0.919	0.861
L&D	0.598	0.723	0.575	- 1	0.626
C&H	0.501	0.613	0,507	0.619	-
Legend:		is Report	.1:9		

Table II-5(a) shows cross-correlation coefficients between the A_0 terms determined here and on four other studies. The relatively high level of correlation between the present results and those of others indicates that this set of correlations is less noisy. Higher correlations have been obtained with the sets of corrections from studies in which azimuthal terms were considered 7,8 than when only A_0 terms were evaluated by simple averaging. 6,9

Table II-5(b) serves to reinforce the conclusion that the present set of A_0 coefficients contains the least amount of noise. If the results published here are treated as independent

variables, the slope of the straight line that relates any two sets of corrections is very close to one, the expected result. For other sets of data, the slope is significantly less than one, indicating greater contamination by noise.

A. M. Dziewonski

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- Seismic Discrimination SATS, Lincoln Laboratory, M.I.T. (31 March 1977), DDC AD-A045453/8.

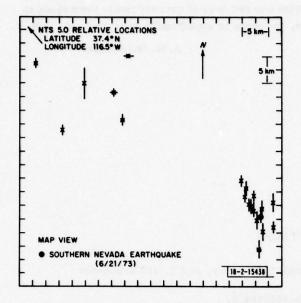


Fig. II-1. Relative epicenters of larger NTS shots, and one earthquake.

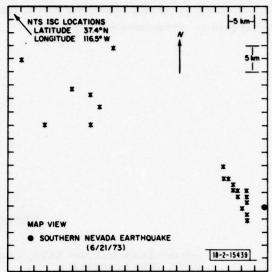


Fig. II-2. Known short epicenters and ISC epicenter for earthquake used in Fig. II-1.

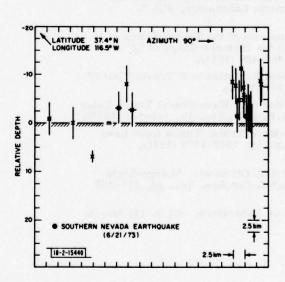


Fig. II-3. Relative depth of NTS shots and earthquake used in Figs. II-1 and II-2.

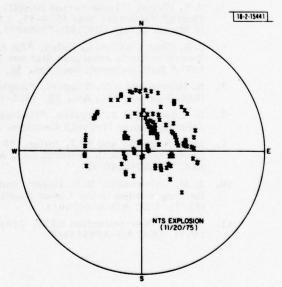


Fig. II-4. Equal-area projection on lower hemisphere of focal sphere. Ray paths computed for a Herrin earth model.

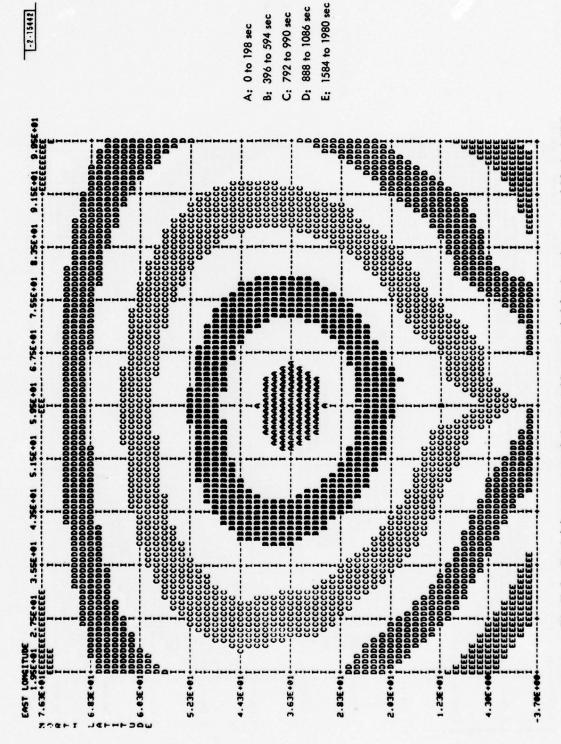
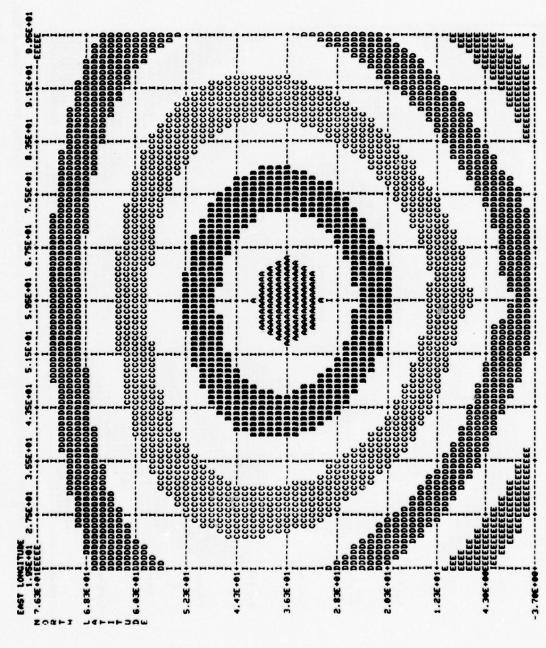


Fig. II-5. Rayleigh group travel times at 20-sec period for locations around Mashad SRO.

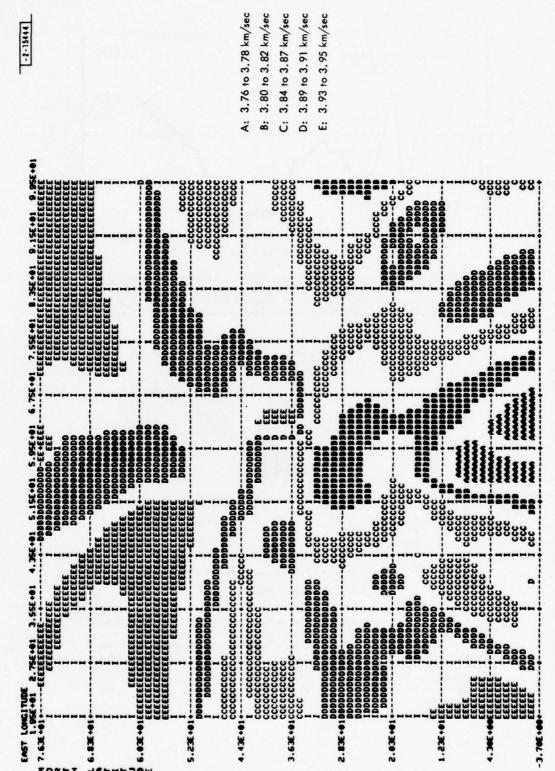




D: 990 to 1155 sec E: 1320 to 1485 sec

A: 0 to 165 sec B: 330 to 495 sec C: 660 to 825 sec

Fig. II-6. Rayleigh group travel times at 40-sec period for locations around Mashad SRO.



-2-15444

Fig. II-7. Average Rayleigh group velocities at 100-sec period for locations around Mashad SRO.

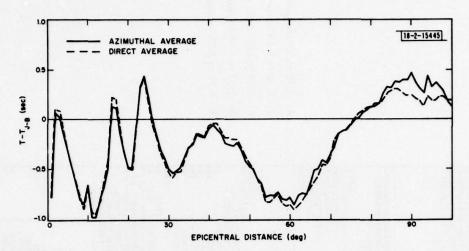


Fig. II-8. Deviations of P-wave travel times from J-B tables for surface focus. Total of 1,657,156 travel times for 24,142 events with depth of focus between 0 and 100 km as located by ISC have been used to derive values shown here. Terms "Azimuthal Average" and "Direct Average" are explained in text.

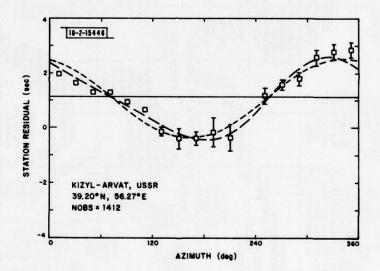
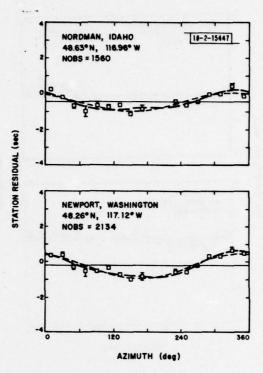


Fig. II-9. Travel-time residuals as a function of azimuth for station Kizyl-Arvat in USSR. Squares represent average residuals for a given azimuth window; error bars indicate standard error of mean, absence of bars indicates that error was less than dimension of a square. Straight line indicates mean residual; short-dashed line is least-squares fit considering average and a term that varies as $\cos{(Az-E_1)}$; long-dashed line is fit that considers also a term $\cos{2}$ ($Az-E_2$).

Fig. II-10. Same as Fig. II-9 but for stations Nordman, Idaho and Newport, Washington. Distance between stations is approximately 40 km. Note similarity between residual patterns at both stations.



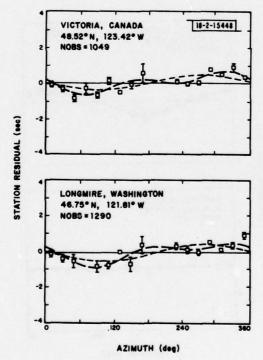


Fig. II-11. Same as Fig. II-9 but for stations Victoria, British Columbia and Longmire, Washington. Distance between stations is approximately 250 km.

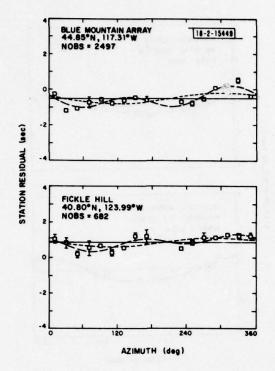
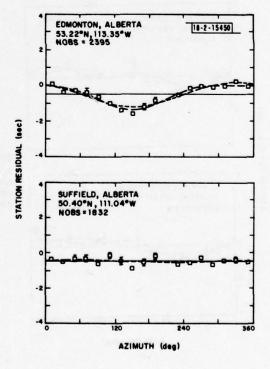


Fig.II-12. Same as Fig.II-9 but for stations Blue Mountain Array, Oregon and Fickle Hill, California. Distance between stations is over 500 km.

Fig. II-13. Same as Fig. II-9 but for stations Edmonton, Alberta and Suffield, Alberta. Distance between stations is 320 km. Note that pattern of residuals is entirely different at both stations. This should be compared with coherent pattern of residuals in Figs. II-10 through II-12. Inference is that source of anomaly observed at Edmonton must be rather shallow.



III. GENERAL SEISMOLOGY

A. AMPLITUDE SPECTRA OF CRUSTAL PHASES FROM A CANADIAN EARTHQUAKE

Amplitude spectra show that earthquake signals originating and recorded in eastern Canada can have signal-to-noise ratios significantly greater than 1 at frequencies as high as 30 Hz. Apparent Q's of crustal phases are in the range of 1000 to 4000. Similarly high Q values have been reported for Lg waves by Ruzaikin et al. 1 for paths crossing central Asia.

Bill Shannon of the Dominion Observatory of Canada provided us with digital SP records of a southern Quebec earthquake of 23 February 1978 (Fig. III-1). The signals were sampled at 60 Hz. The velocity sensitivity of the recording system is flat between 2 and 15 Hz, and drops by a factor-of-10 between 15 Hz and the Nyquist frequency of 30 Hz. The amplitude spectra are from 10-sec samples of P, S, and Lg wavetrains recorded at MNQ (Fig. III-2) which is the most-distant station from the source, an arc distance of 5°.

A comparison of the noise amplitude spectrum in Fig. III-3(a) with the signal amplitude spectra [Figs. III-3(b) through (d)] shows that signal strength in the pass band from 1 to 25 to 30 Hz is significantly above the noise level. Upper bounds on attenuation or equivalently lower bounds on Q were estimated from the slopes of displacement amplitude spectra. Single-station estimates of absolute Q are not possible without knowing a priori the source spectrum. The spectral slopes are given by

$$\frac{\log I(f_2) - \log I(f_4)}{\log (f_2) - \log (f_2)} \tag{III-1}$$

where I(f) is the displacement amplitude spectrum which is equated to $I_0 e^{-\pi f/QU}$ for an estimate of Q. The velocity of energy propagation U is assumed to be 8.13, 4.72, and 3.60 km/sec for compressional, shear, and Lg propagation, respectively. Slopes were measured in the band of the flat velocity response and the high-frequency band. The results are given in Table III-1. If the slopes are entirely the result of signal diminution from attenuation, the corresponding Q's are given in Table III-2. The highest Q's are estimated for the crustal-phase Lg which suggests that this phase propagates with a mechanism that is distinct from that for the crustal body waves P and S. A wave guide effect could account for anomalously high Q values if, for example, longer-period energy was preferentially leaked out of the guide. Such a mechanism

	TABLE III OBSERVED S	
	Band 1 (2 to 15 Hz)	Band 2 (15 to 30 Hz)
P	-1.00	-3.35
S	-1.30	-3.00
Lg	-1.00	-3.00

	TABLE III Q	-2
	Band 1 (2 to 15 Hz)	Band 2 (15 to 30 Hz)
P	2500	1400
S	2000	2940
Lg	3430	3620

could account for extremely high Q values reported by Walker et al.³ for Sn propagating through the oceanic lithosphere in the western Pacific (Sean Solomon, personal communication).

T. J. Fitch M. W. Shields

B. SCATTER IN OBSERVED mb VALUES

The scatter of individual station m_b values about the network mean \overline{m} is well known. However, the details of the physical processes which lead to this scatter are much less well known. In particular, it is very difficult to assess how much improvement in both amount of scatter and bias in the network mean can be obtained by a process of path calibration.

For simplicity, let us write the magnitude observed at the ith station in a network as

$$m_i = log(A/T)_i + Q_i(\Delta, L) + \phi_i$$
 (III-2)

Here, A_i and T_i are the observed amplitude and period, Q_i is the standard Gutenberg-Richter distance-depth correction, and ϕ_i summarizes all those effects which lead to a departure of m_i from the true event magnitude m.

The various components of ϕ can be listed as follows:

- (1) Departures of the Gutenberg-Richter Q correction from the true global mean correction corresponding to a particular attenuation t*.
- (2) Regional variations from the global mean correction, including regional variations in t*.
- (3) Near-receiver effects (i.e., station amplitude corrections).
- (4) Near-source effects.
- (5) Radiation pattern.
- (6) Quasi-random scattering by inhomogeneities.
- (7) Measurement errors.

Of these, the first five are essentially deterministic and could, at least in principle, be removed by a process of network calibration. The last two are stochastic quantities. Measurement errors are in most cases very small. Scattering appears to occur mainly in the vicinity of the receiver, but there have been suggestions that scattering near the source may sometimes be significant.

Before the application of corrections, ϕ seems to be normally distributed, with standard deviation, averaged over many events, typically in the range 0.3 to 0.4 (see Refs. 3 through 5). North found that the application of corrections for station amplitude biases leads to a reduction in this standard deviation of about 15 percent. Figure III-4 shows the distribution of standard deviations observed at North's 72-station network for those events in the ISC Catalog with mb less than 6.0, and at least 15 stations reporting. The distribution of standard deviations is skewed, as would be expected, since the distribution of sample variances for a normal parent population is a chi-square distribution. The reduction in mean standard deviation, from 0.356 to 0.311, is about 12 percent.

The reduction in the standard deviation that can be obtained by using a better global mean amplitude-distance correction appears to be somewhat less than 10 percent. Veith and Clawson 7

were able to reduce the mean standard deviation of USCGS data file earthquakes from 0.381 to 0.350 by this means. Evernden and Clark⁸ also revised the amplitude-distance curve for stations in the U.S., and Evernden and Kohler⁹ report a reduction of standard deviation to 0.26 from data in the earlier study, though they give no information about how this number was obtained. It appears that the distributions of both stations and events were limited in extent, and they may have succeeded in removing some regional variations in t*.

Scattering from inhomogeneities near the receiver appears to be very sensitive to source location, 4,10 and may set a practical limit to the reduction in scatter achievable for a global network. Evidence from studies of LASA 11 and NORSAR 10 suggests that this scatter has a standard deviation of about 0.25 over distances of tens of kilometers. Frasier 10 considered the amplitude variations at NORSAR for 1-Hz signals observed from 11 events at various azimuths to the array. Standard deviations of individual subarray center sensors relative to the array beam were found to lie in the range 0.13 to 0.30. The average standard deviation for these 11 events was 0.24.

Two conclusions can be made immediately. The process of path calibration is likely to reduce the standard deviation of m_b values from about 0.30 to about 0.25, unless incredibly detailed calibrations are attempted. Also, the statement of Evernden and Kohler⁹ that this standard deviation can be reduced to 0.21, or even 0.15 for a high-quality network, seems completely unjustified. This agrees with the conclusion of Ringdal, who used a very different approach.

M. A. Chinnery

C. ON ESTIMATING YIELDS FROM BODY-WAVE OBSERVATIONS

In a previous SATS, 12 we gave expressions for the body waves radiated by a moment-tensor point source. If a pressure is applied to the walls of a small cavity with a time history given by

$$P(t) = P_{O}(1 - e^{-t/\tau})$$
 (III-3)

where P_0 is the asymptotic limit and τ is a time constant, then the far-field radial displacement will be

$$\vec{s}_{r}(t,r) = \frac{M}{\alpha \sigma^{3} r} \exp\left[-\frac{t - r/\alpha}{\tau}\right] . \tag{III-4}$$

Here, M is the isotopic moment defined as P_0 times the volume of the cavity, and ρ and α are the density and P-wave velocity in the source region. This result allows us to calculate the radiated seismic energy.

The energy flux is

$$\vec{S} = -\frac{\partial \vec{s}}{\partial t} \cdot T \tag{III-5}$$

where T is the propagating stress tensor. If Eq. (III-4) is substituted into Eq. (III-5) and the result is integrated over a surface surrounding the source, the total radiated energy is

$$E = \frac{2\pi M^2}{(\lambda + 2\mu) (\alpha \tau)^3} . \qquad (III-6)$$

Here, λ and μ are the Lamé parameters in the source region. Incidentally, Eqs. (III-4) and (III-6) are inconsistent with cube-root scaling. This is not surprising since cube-root scaling is based on near-field observations where $1/r^2$ terms are important.

Equation (III-6), although simple in form, shows the inherent difficulty in yield estimation. To begin with, the energy or yield is proportional to the amplitude squared of the observed P waves, since they will be proportional to the moment M. This is reasonable since the energy in mechanical systems is generally proportional to the amplitude squared of the observed vibrations. The real problem is in the denominator, where the energy is proportional to the inverse cube of the P-wave velocity times the time constant. It is also inversely proportional to the Lamé parameters. If we define a characteristic length

$$L = \alpha \tau \tag{III-7}$$

then the fractional change in yield due to a fractional error in estimating (or measuring!) L is

$$\frac{dE}{E} = -3\frac{dL}{L} \quad . \tag{III-8}$$

In other words, a 30-percent error in estimating L produces an order-of-magnitude error in the calculated yield. Similarly, a 50-percent error in estimating M also produces an order-of-magnitude error in E. The former effect should dominate, if only because measuring the width of a seismic pulse is difficult in practice.

What makes this state of affairs even more depressing is the implied assumption in Eq. (III-4) that the seismic amplitudes have been accurately reduced to the focal sphere in order to calculate the moment. This means correcting for: the effects of the free surface at the stations, geometrical spreading, and earth attenuation. In addition, because the source is within a P wavelength of the free surface, separating the primary and depth phases will not be straightforward. The inescapable conclusion of Eq. (III-6) is that there are many significant linear elastic questions to be settled before embarking on a nonlinear hydrodynamic approach to yield estimation.

D. W. McCowan

D. LATERAL VARIATIONS IN MANTLE LOVE-WAVE DISPERSION FROM SRO DATA

In a recent SATS, 13 preliminary results of a study of mantle wave (100- to 500-sec period) dispersion have been given. The high sensitivity and broad dynamic range of the SRO instruments permit detection and analysis of signals at such long periods from events as small as $M_s = 6.5$. Enough data have now been collected for a preliminary regionalization of mantle Love-wave dispersion. In all, 207 paths from the SRO stations to the 34 events shown in Fig. III-5 have been used. Phase velocity has been measured from pairs (G2, G4) and (G3, G5) on each seismogram. This double measurement for each path provides a valuable check on the accuracy of the results obtained. Phase velocities from (G2, G4) and (G3, G5) differed by less than 0.005 km/sec for 53 paths, and by less than 0.010 km/sec for 109 paths. Paths for which the two measurements differed by more than 0.010 km/sec were rejected.

The average dispersion curve differed by, at most, 0.025 km/sec (~0.5 percent) from that given by the (interpolated) normal-mode eigenfrequencies of for model PEM-A. Among its other features, this model has been designed to fit the observed normal-mode eigenperiods to an overall rms error of 0.183 percent. This fit to an average earth model is much better than that given by previous data and is presumably due not only to the better data quality, but also to the greater number of paths sampled, giving a closer measurement of average earth properties.

Following previous studies, 15,16 we have regionalized the earth into structural provinces of oceanic, stable continental, and tectonic, and inverted the data obtained to determine average

dispersion for these three regions. The variations in regional dispersion obtained in this manner were significantly less (by a factor of 3) than that of a previous mantle Love-wave study. However, using Rayleigh waves, other workers 16,17 have also found less variation than that given in the same study.

Following the demonstration from shorter-period (<100-sec) Rayleigh-wave studies ^{18,19} of substantial variations in oceanic dispersion with age, a regionalization taking this into account has been carried out by Ocal. ¹⁷ However, Ocal had insufficient data to invert for oceanic variations and assumed dispersion for age-dependent oceanic models ¹⁹ to invert only for 3 continental regions.

The present data base is adequate to invert simultaneously for several oceanic regions as well as these 3 continental structures. The oceans were divided into 3 age zones (0 to 30, 30 to 60, and 60+ million Year Age) and the rest of the world into stable shield, foldbelt, and tectonic. The last two divisions correspond to regions of active shallow and deep (subduction zone) seismicity, respectively. Since these non-oceanic divisions differ somewhat from those of Ocal, 17 they are shown in Fig. III-6. An attempt was made to resolve more than 3 oceanic regions, but when this was done, resolution was degraded because the width of the resulting smaller areas was comparable to the wavelength used.

The results of an inversion to determine regional dispersion in the 3 oceanic regions and the shield, foldbelt, and tectonic zones are shown in Fig. III-7. For purposes of clarity, the oceanic zones are shown separately from the others, but at any given period the six points shown are the result of an independent inversion. The bars denote plus-or-minus one standard deviation about the mean. The dispersion in each case is shown as deviations from the mean of all observations. The 3 oceanic regions exhibit dispersion very close to that predicted by models of the oceanic lithosphere as a function of age, ¹⁹ and the slower dispersion in youngest (<30 M.Y.) zones is particularly marked. The two older age zones are not as well separated as predicted by the appropriate models.

The "continental" dispersion curves exhibit expected behavior in that shield is fastest and foldbelt is slowest. Note that the dispersion for the latter is slower at shorter periods, gradually merging with the other two. The tectonic region has dispersion characteristics surprisingly close to the mean, in view of the low velocities known to occur above the descending lithosphere slabs in these areas. A similar result has been obtained by Ocal 17 who suggested that the descending high-velocity slab outweighs the effect of the uppermost low-velocity areas.

In all cases, the dispersion at periods in excess of the 400-sec period is statistically almost indistinguishable. To what extent this is real, and not dictated by the somewhat higher variance of the data input to the inversion, is unclear. Preliminary calculations of dispersion for various types of models of upper-mantle structure indicate, however, that the dispersion differences observed do not require any velocity variations below 200 km depth. Although the resolution of higher modes at greater depths is substantially better than that of the fundamental mode dispersion studied here, the present data do provide fairly good resolution down to ~500 km depth.

R. G. North

E. ANALYSIS OF BROAD-BAND ANMO RECORDINGS OF DEEP EVENTS

In the latter half of 1977, the backup SRO installation at Albuquerque, New Mexico was operated in a broad-band mode during the off hours. This was accomplished by removing the SP

shaping filter and feeding the output of the seismometer directly to the digitizer. Since the antialias filter had been removed previously, the resulting instrument response was just that given for the Geotech 36000 seismometer by McCowan and Lacoss. In the period of time when broadband data were recorded, we retrieved and analyzed five Fiji-Tonga events all occurring at depths greater than 600 km. These were selected because of the likelihood that they had small source volumes and, consequently, impulsive waveforms. Figures III-8 and III-9 show the results of this analysis on one event, an m_b = 5.4 shock occurring on 25 September 1977 at a depth of 606 km.

The second trace in both figures is the impulse response of the seismometer convolved with constant Q operators with attenuation times of 0.5 and 0.7, respectively. The third traces are the least-squares shaping filters which convert the second traces into the first, which is the recorded data. These are interpreted as the actual earth input to the seismometer. The fourth traces are the result of convolving the second and third traces, and can be seen to be accurate copies of the data. Because inverse filtering introduces substantial numerical noise, the fifth traces are the third traces lowpass-filtered.

The results show that the lowpass-filtered earth motion, after the effects of the instrument and earth attenuation have been removed, is more impulsive for the case where $t^* = 0.7$ than it is for $t^* = 0.5$. If the original assumption about the sharp source time function is correct, then this result contrasts with the lower values of t^* reported by Frasier and Filson²¹ for explosions. The other impulse occurring approximately 2 sec after the P wave is PcP which, at this distance, is superimposed on P. This phase is unresolvable on the original recording.

Since this result is based on the assumption that the source is impulsive, it produces the largest value of t* consistent with the data. Conservation of energy, however, requires that the stress loading in the source region be relieved in a nonzero time interval, which would tend to lower the observed t*.

In principle, this method is a way of measuring Q using only a single station. To be practical, however, considerable data should be available for many deep shocks at the same hypocentral location, and more realistic source time functions should be used as they become available.

D. W. McCowan

F. TRANSFER FUNCTIONS FOR SEISMIC STATIONS USED FOR MONITORING AT REGIONAL DISTANCES

Selecting response characteristics for seismic stations whose primary purpose is to collect data in the "regional" distance range, $0 \le \Delta \le 20^\circ$, involves a compromise between providing adequate data bandwidth and introducing complexity into the time-domain impulse response. On the one hand, if the passband of the instrument extends close to the Nyquist frequency, typical anti-alias filters have such steep skirts that the respective time-domain effects dominate the impulse response. On the other hand, if the Nyquist frequency is chosen to be substantially higher than the instrument passband, then the resulting data rates for SP responses are excessive. With this trade-off in mind, we have selected LP and SP responses which provide a reasonable balance between good bandwidth and simplicity in the time domain.

The LP frequency and time-domain displacement responses are shown in Figs. III-10 and III-11. The sampling rate is 1 Hz. This is the same as the present SRO configuration, except that the 6-sec notch filter has been removed. As can be seen, the amplitude response is down 40 and 80 dB at the microseism and Nyquist frequencies, respectively, from its peak at the

25-sec period. The corresponding time-domain impulse response shown in Fig. III-11 is similar in shape to other LP systems, e.g., the WWSSN. Removal of the notch filter should facilitate recovery signals in the microseism band when their S/N are high enough to warrant it. The poles and zeros of the LP Laplace transform are given in Table III-3.

LP System	1
Poles	Zeros
s + 4.648 ± 3.463j	,5
s + 0.1179	s + 50.07
s + 40.73	s + 0.1256
s + 0.1500	
s + 100.0	
s + 264.0	
$s + 0.2010 \pm 0.2410$	
$s + 0.1337 \pm 0.1001$	
s + 0.0251	
s + 0.00924	
$s + 0.8547 \pm 0.2555$	
s + 0.5415 ± 0.6834	
SP System	
Poles	Zeros
	4
s + 4.648 ± 3.463j	3
s + 0.1179	s + 0.1256
s + 40.73	s + 50.10
s + 0.1500	
s + 100.0	
s + 264.0	
s + 16.73 ± 3.397j	
s + 63.29 s + 63.29	
s + 63.29 s + 100.0	

The SP amplitude response is shown in Fig. III-12. It peaks at 3 Hz and drops off 24 dB at the Nyquist frequency. This is the same as the present configuration of the SRO except that the sampling rate has been increased to 40 Hz. As previously noted, ²⁰ sampling this response at 20 Hz provided only marginal alias rejection. Increasing the sampling rate by an octave doubles this rejection. It also enhances the action of "natural" anti-alias filtering through earth attenuation. In this frequency range, the effect of attenuation is nonlinear with frequency: doubling the system bandwidth more than doubles the effect of Q.

Time-domain displacement impulse responses are shown in Figs. III-13 and III-14 for two values of the attenuation parameter t^* . The first, $t^* = 0.1$ in Fig. III-13, is a value characteristic of crustal-phase propagation in the regional distance range. The other, $t^* = 0.5$ in

Fig. III-14, is characteristic of teleseismic P-wave propagation. As can be seen in Fig. III-14, attenuation in this frequency band introduces a substantial group delay. This is an unavoidable consequence of the mechanism of attenuation, and will have to be accounted for when using high-frequency arrival times to locate regional events. The poles and zeros of the SP Laplace transform are also given in Table III-3.

D. W. McCowan

G. SEISMIC APPLICATIONS SOFTWARE

In previous Semiannual Technical Summaries, we mentioned our waveform database format — a standardized, general format for seismic data in the UNIX system. We also described the programs developed to generate data in this format (by reading magnetic tapes or retrieving data from the Datacomputer), and to interactively display it on the Tektronix scope. Now we have added to these facilities by providing a set of general routines in both C and Fortran that perform the basic functions necessary for working with a waveform database. Using these general routines, we have started to provide a package of basic seismic processing programs similar to those which comprised our PDP-7 Seismic Data Analysis Console.

1. The Waveform Database Format

A waveform database is a group of UNIX files that contain seismic waveform data and descriptive information in a specified format. A database name may be up to 6 characters long, and the file names are created by adding appropriate suffixes to the database name. The essential parts of a waveform database are the gram index file and the gram files. The other component files may or may not exist, but certain processing programs will expect certain files to be present. Figure III-15 shows the relationship between files in a waveform database, and Table III-4 lists the components of the alphanumeric waveform database files.

The gram index file ("dbname. gi")

The gram index file is an alphanumeric file, each line of which describes a seismogram. The seismograms themselves are found in the gram files described below. Each entry in the gram index file may also refer to an event described in the database event file. In this case, the gram index file may contain arrival information relating to that event. Every waveform database must contain one (and only one) gram index file.

The gram files ("dbname. #.g")

For each entry in the gram index file, there must be a gram file, which is a binary file that contains the actual data points of the seismogram. Each gram file has a header that specifies the number of points to follow and the data type, which may be either integer or floating point.

The event file ("dbname. ev")

The event file is an alphanumeric file, each line of which describes a seismic event that may be associated with some of the seismograms in the database. An event file is created by the programs that set up Datacomputer retrieval requests from seismic bulletins, and is used by programs such as mkphases and rotate (described below).

TABLE III-4

COMPONENTS OF THE WAVEFORM DATABASE FILES

Gram Index File

Name of seismogram file
Station name
Start date and time of data
Number of data points
Sampling interval between data points
Calibration
Instrument code

LP or SP Orientation Filtered or unfiltered Beam or single sensor Type of instrument

Arrival information

Event number
Distance of event from station
Azimuth of event from station
Phase code
Arrival date and time

Comment

Event File

Event number
Origin date and time
Latitude
Longitude
Depth
mb
ms
Geographic region code
Seismic region code
Geographic region name

(The following items are taken from the Datacomputer event summary file and are present only for data originally obtained from the Datacomputer)

Datacomputer event number
Number of waveforms in waveform file
Number of SP waveforms in waveform file
Number of LP waveforms in waveform file
Source of location information
Method of calculating depth
Number of stations used in computing location
Number of stations used in computing mb
Number of stations used in computing mb

Marker File

Gram file name Sample number marked Marker name

The marker file ("dbname. mk")

Each entry in the alphanumeric marker file describes a named "flag" that has been associated with a particular data point in a particular seismogram. Markers can be created by using the display program cursor, the mkphases program, or by using the editor. They can be displayed by the display program, and are used by programs such as measure and window.

The transform files ("dbname. #.t")

These files are similar in name and format to the gram files, but each contains the complex Fourier transform of the associated gram file. They are created by the transform program and used by the ampspect and phaspect programs.

The display files ("dbname. #.d")

Each display file contains a description of a particular display view of the database. They are usually created and used by the display program, but may also be modified by user programs.

2. Dhsubs

Dbsubs is a set of subroutines designed to make it easier for applications programmers to work with waveform databases. They perform all the basic functions and take care of such details as formatting, error-checking, constructing filenames, and other sorts of housekeeping tasks.

The subroutines are oriented around two basic scenarios. The first allows the user to sequentially read an input database and modify its marker file, create transform files, or produce any output that does not fall under the database system. The second scenario allows the user to read sequentially from one input database and produce a modified output database. Nearly all the waveform operations that have been suggested to us so far fall under these two basic scenarios.

The dbsubs package includes the following subroutines.

setup

Gets the database arguments from the command line and performs initialization. If an output database is being created, setup copies the input event and marker files to the output database.

getgil

Reads the next sequential line from the input gram index file, unpacks the parameters, and returns them in a structure (in C) or a labeled common area (in Fortran). Sets a flag if the end of the gram index file is reached.

putgil

Takes the gram index parameters from a structure (in C) or a labeled common area (in Fortran), formats them, and writes a line to the output gram index file. It will properly insert the output database name into the output gram file name.

opgin

Given a gram number, opgin opens the corresponding input gram file and reads the header, leaving the pointer positioned to read the first data point. It will return the number of samples

and the data type found in the header. Once opgin has been called, the user may utilize the standard binary read routines on the gram file.

Opgout

Given a gram number, number of samples to be output, and data type, opgout creates a corresponding output gram file and writes out the header, leaving the pointer positioned to write the first data point. Once opgout has been called, the user may utilize the standard binary write routines on the gram file.

optin

Given a gram number, optin opens the corresponding input transform file and reads the header, leaving the pointer positioned to read the first data point. It will return the number of samples found in the header. Once optin has been called, the user may utilize the standard binary read routines on the transform file.

optout

Given a gram number and number of samples to be output, optout creates a corresponding output transform file and writes out the header, leaving the pointer positioned to write the first data point. Once optout has been called, the user may utilize the standard binary write routines on the transform file.

getev

Given the event number from the gram index line, getev locates the corresponding line in the input database event file and reformats it into a structure (in C) or a labeled common area (in Fortran).

apndcm

Opens the comment file, adds the current date and time to the end of the file, and returns to the calling program, leaving the file open and the pointer positioned for further writing. If the output database does not contain a comment file, one will be created.

marker routines

There are several routines provided to read and write marker files. They have been designed to handle three basic situations, or any combination thereof:

- (a) Markers are being created by the program. In this case, "apndmk" can be used to add new markers to the output marker file.
- (b) Marker values are used as input to the program. In this case, "getmk" can be used to look for specific named markers in the input database.
- (c) All markers in the input database must be modified before being written to the output database. In this case, use "clrmk" to clear the output marker file, "grammk" and "nextmk" to get all the input markers for a given gram, and "apndmk" to write the modified markers to the output database.

3. Seismic Processing Programs

Before starting to work on these programs, a survey was taken asking the group members to rate a list of suggested programs in terms of their usefulness. Then we proceeded to implement the programs roughly in the order of priority, adjusted slightly to favor the programs that could be completed most quickly. The following programs (listed in order of priority) have been completed and released.

dec

Shortens the gram files by decimating, that is retaining only every nth point. As with all generally written waveform database programs, this involves modifying the gram index file to change the "sampling interval" and "number of samples" parameters, and modifying the marker file to reflect the change in sample numbers caused by the decimation.

measure

Types out the exact time and amplitude at a specified marker. This would usually be used in conjunction with the interactive display program.

mkphases

For a database containing event information, mkphases computes theoretical phase arrival times and creates labeled markers to flag each of the resulting data points.

window

Shortens the gram files by retaining the segment lying between preset "start" and "end" markers.

markpeak

Adjusts a marker to fall on the nearest peak. This is useful if the marker was originally set by using the Tektronix cursor, which cannot resolve adjacent points unless the waveform is blown up on the screen.

wdup

Makes a copy of a waveform database.

wmv

Moves or renames a waveform database.

floatgram

Converts the grams of a database to floating point.

interam

Converts the grams of a database to integer, scaling if necessary.

gramdump

Dumps a (binary) gram file in alphanumeric format.

wfix

Deletes gram files not referred to in the gram index file. (This would usually be due to purposeful editing of the gram index file by the database owner.)

wrm

Deletes a waveform database.

The following programs are currently in progress.

filter

Applies a 3-pole Butterworth filter to all the gram files in the input database, and creates an output database containing the filtered gram files. Has options to specify phase-free filtering, the order of the desired filter, a decimation factor, the filtering of only certain grams, and the filtering of only the first n points in each gram processed.

transform

Computes the Fourier transform of each gram in a database and creates transform files to contain the results.

ampspect

Plots an amplitude spectrum from a waveform database transform file.

phaspect

Plots a phase spectrum from a waveform database transform file.

The following programs are on the list to be implemented.

rotate

Given a database containing 3-component data and event information, create a new database replacing the east and west components with computed radial and transverse components.

getphase

Shorten the gram files by computing a theoretical phase arrival and selecting the data that fall in that window.

concatenate

Combine two or more waveform databases.

L. J. Turek D. A. Bach

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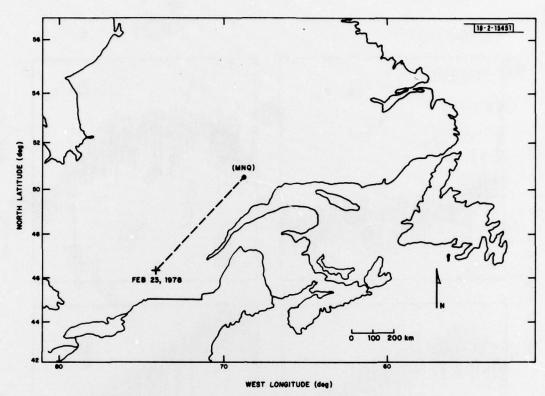


Fig. III-1. Map of northeastern North America, showing location of 23 February 1978 earthquake relative to station MNQ.

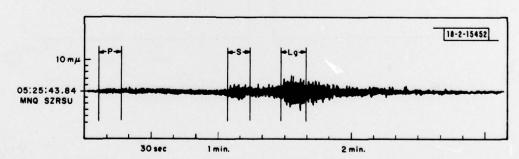


Fig. III-2. 10-sec samples of P, S, and Lg wavetrains recorded at MNQ.

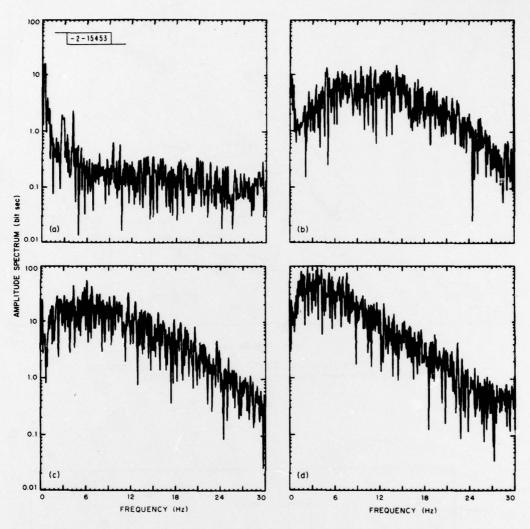


Fig. III-3. (a) Noise amplitude spectrum, (b) P-wave amplitude spectrum, (c) S-wave amplitude spectrum, and (d) Lg amplitude spectrum.

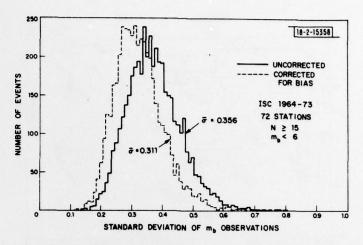


Fig. III-4. Distribution of observed m_b standard deviations before and after application of station amplitude corrections. Data are taken from ISC Catalog 1964-73, for events with $m_b < 6.0$ and at least 15 stations reporting.

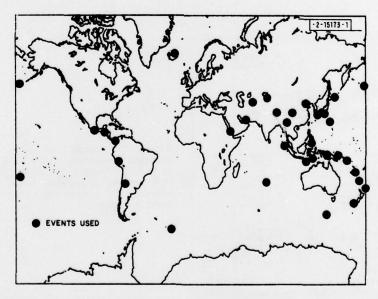


Fig. III-5. Events of $M_{\mbox{\scriptsize g}}\geqslant 6.5$ during 1976-78 used to provide data for mantle Love-wave study.

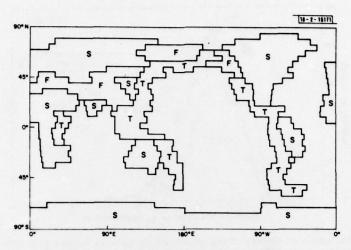


Fig. III-6. Continental division of earth into shield (S), foldbelt (F), and tectonic (T) regions.

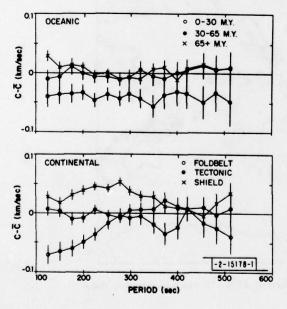


Fig. III-7. Results of Love-wave phase velocity regionalization into 3 oceanic and 3 continental regions. Dispersion is shown as difference from mean phase velocity \overline{C} . Error bars denote one standard deviation.

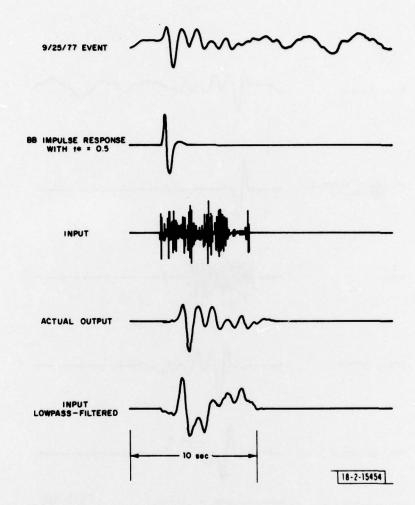


Fig. III-8. Broad-band processing results for a deep Fiji-Tonga event with attenuation time t^{\star} = 0.5.

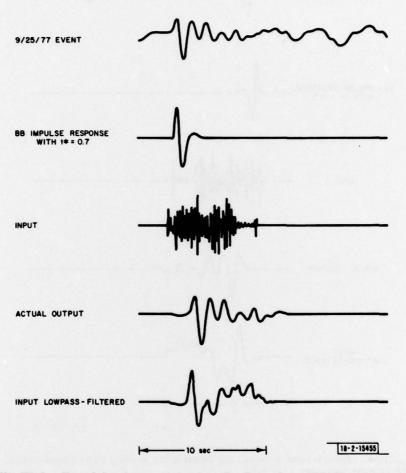
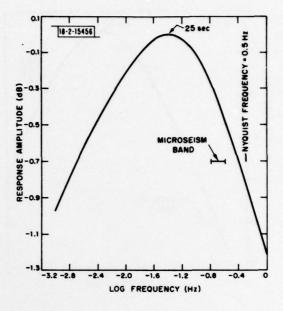


Fig. III-9. Broad-band processing results for a deep Fiji-Tonga event with attenuation time t^{\star} = 0.7.

Fig. III-10. SRO LP displacement response without 6-sec notch filter.



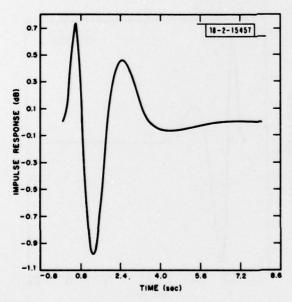


Fig. III-11. SRO LP impulse response without 6-sec notch filter. Sampling rate = 1 Hz.

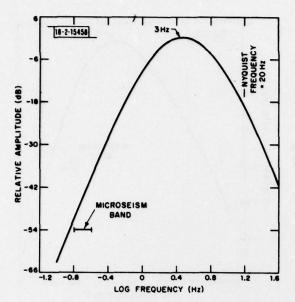
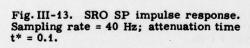
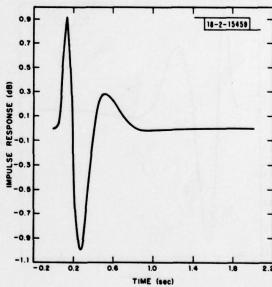


Fig. III-12. SRO SP displacement response.





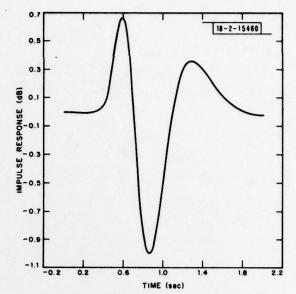


Fig. III-14. SRO SP impulse response. Sampling rate = 40 Hz; attenuation time $t^* = 0.5$.

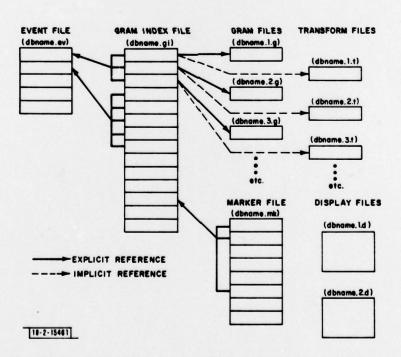


Fig. III-15. Relationship between files in a waveform database.

GLOSSARY

bpi	Bits per Inch
CCD	Conference of the Committee on Disarmament
CPU	Control and Processing Unit
CTBT	Comprehensive Nuclear Test Ban Treaty
DOE	U.S. Department of Energy
FFT	Fast Fourier Transform
ISC	International Seismological Center
ISM	International Seismic Month
J-B	Jeffreys-Bullen Tables
LP	Long Period
MP	Medium Period
NEIS	National Earthquake Information Service
NTS	Nevada Test Site
PDE	Preliminary Determination of Epicenter
SATS	Semiannual Technical Summary
SDAC	Seismic Data Analysis Center
SDMS	Seismic Data Management System
S/N	Signal-to-Noise Ratio
SP	Short Period
SRO	Seismic Research Observatory
USGS	U.S. Geological Survey
WMO	World Meteorological Organization
wwssn	World-Wide Standard Seismograph Network

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